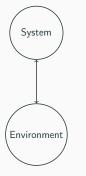
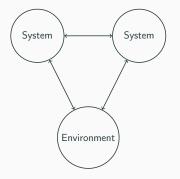


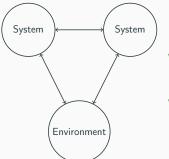
Efficient Trace Encodings of Bounded Synthesis for Asynchronous Distributed Systems

Jesko Hecking-Harbusch, **Niklas O. Metzger** October 30, 2019

Saarland University - Reactive Systems Group





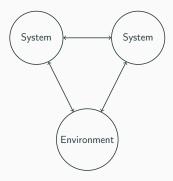


- Distributed Systems are hard to synthesize ¹
- ✓ Petri games as framework for distributed synthesis ²
- ✓ Bounded Synthesis for Petri games³

¹Pnueli and Rosner, "Distributed Reactive Systems Are Hard to Synthesize".

²Finkbeiner and Olderog, "Petri Games: Synthesis of Distributed Systems with Causal Memory".

³Finkbeiner, "Bounded Synthesis for Petri Games".

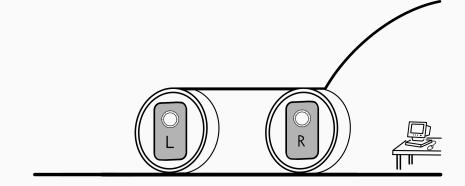


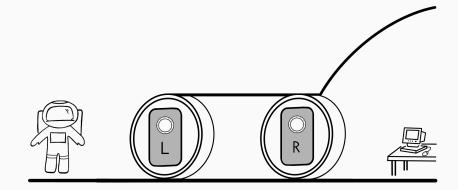
- Distributed Systems are hard to synthesize ¹
- ✓ Petri games as framework for distributed synthesis ²
- ✓ Bounded Synthesis for Petri games³
- Asynchronous nature is encoded to interleaving

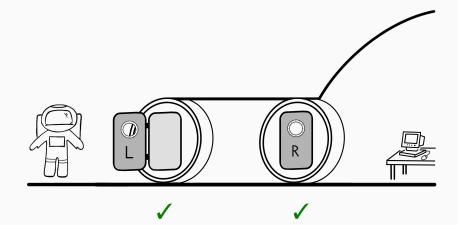
³Finkbeiner, "Bounded Synthesis for Petri Games".

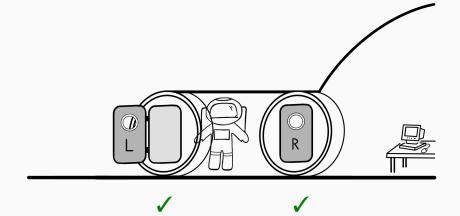
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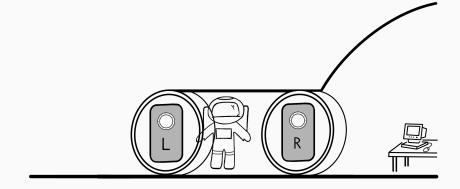
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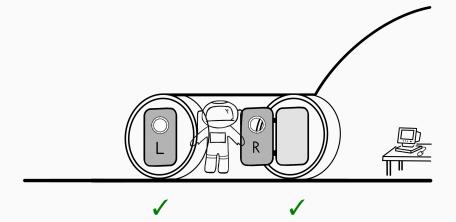


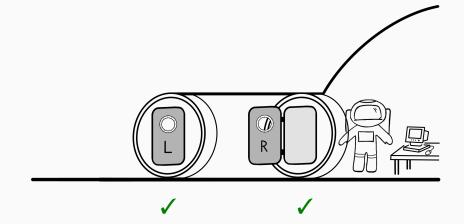


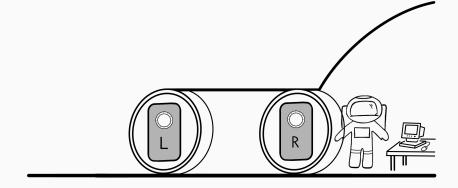


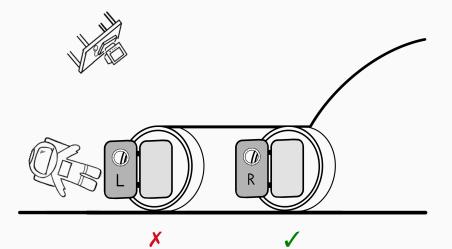


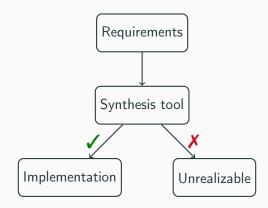




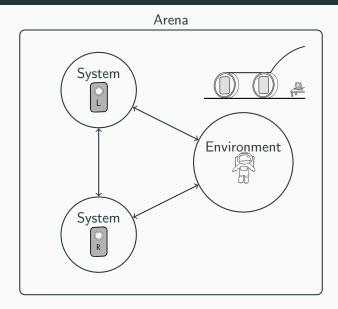




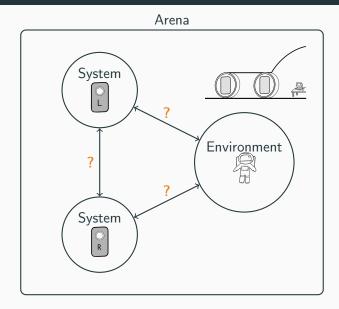




Synthesis of Distributed Systems as a Game



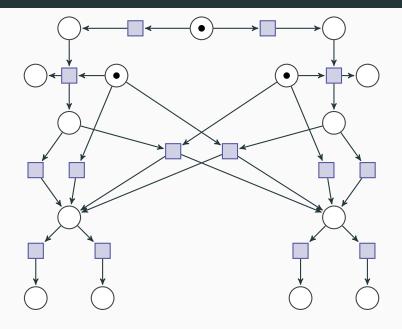
Synthesis with Local Information



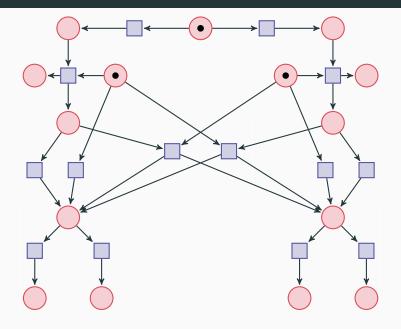
- 1. Petri Games
- 2. Bounded Synthesis
- 3. True Concurrency in Petri Games
- 4. True Concurrency in Bounded Synthesis of Petri Games

Petri Games

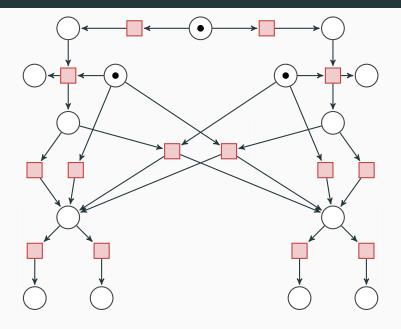
Petri Net as Game Arena of Petri Game



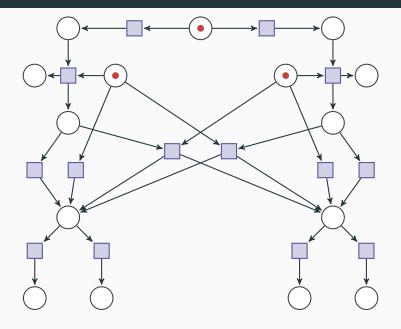
Places \mathscr{P} in a Petri Net



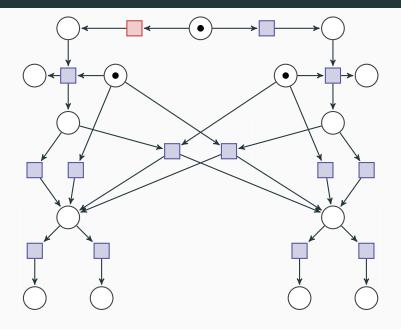
Transitions \mathcal{T} in a Petri Net



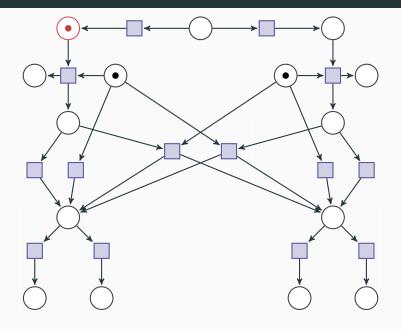
Tokens in a Petri Net



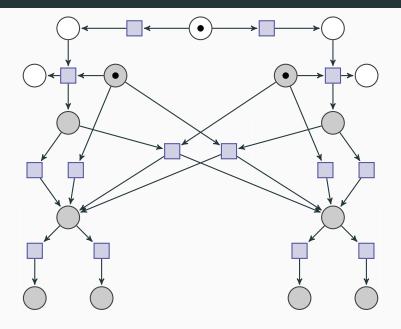
An enabled transition...



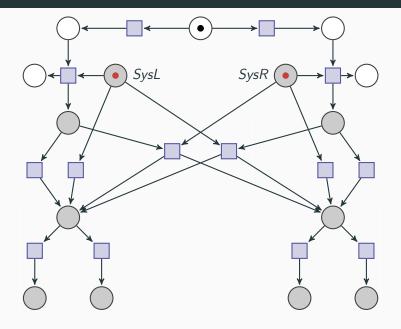
...can be fired in a Petri Net



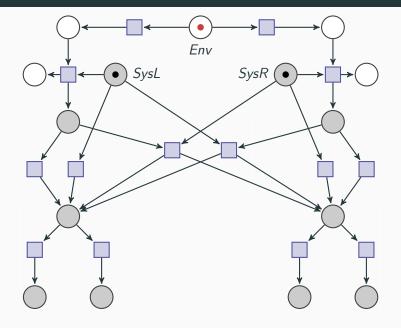
From Net to Game



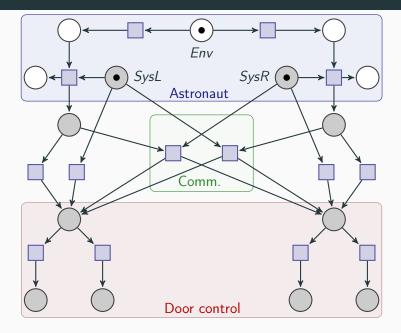
Two System Players



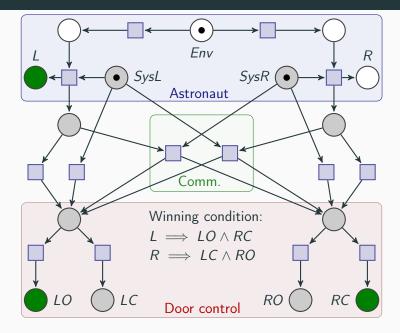
One Environment Player



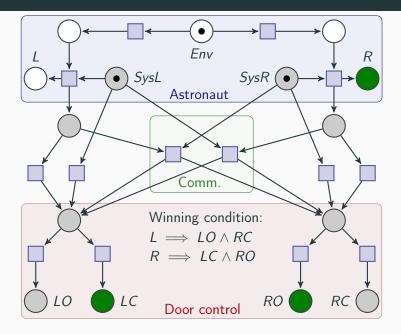
Airlock as Petri Game



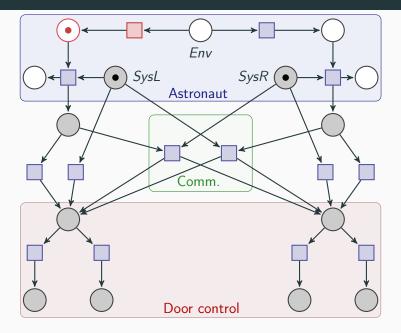
Winning Conditions of the Petri Game



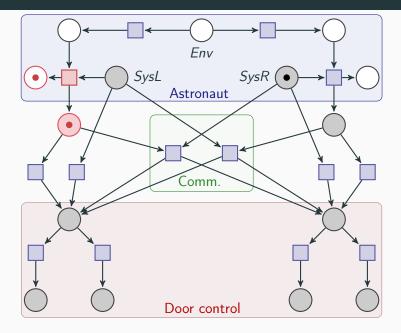
Winning Conditions of the Petri Game



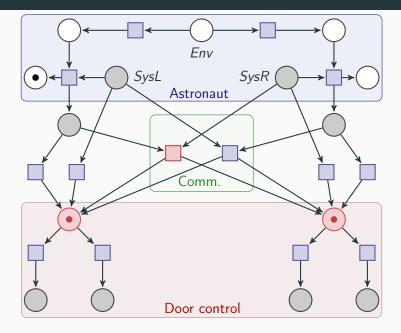
Decision for left Door



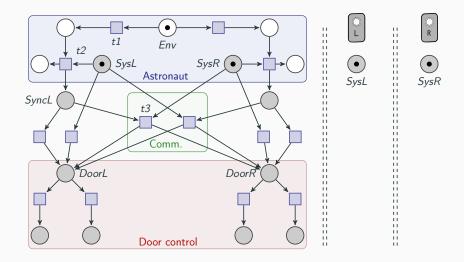
Synchronization with the System



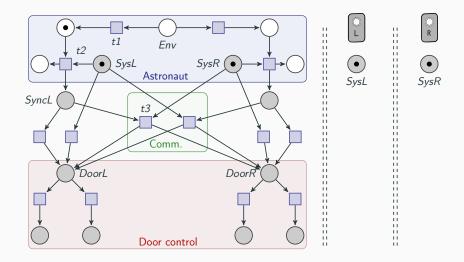
Exchange of Information



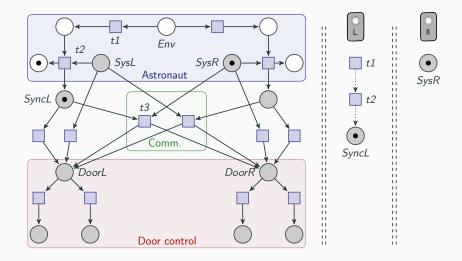
Memory Model of Petri Games: Causal Past



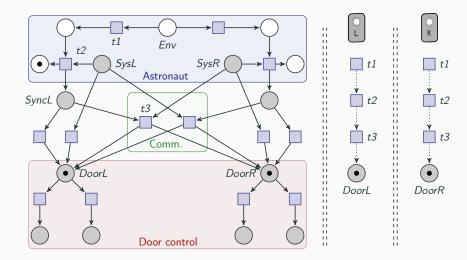
Memory Model of Petri Games: Causal Past



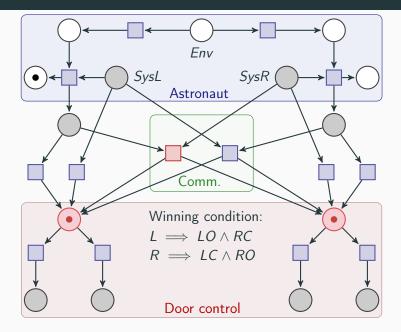
Memory Model of Petri Games: Causal Past



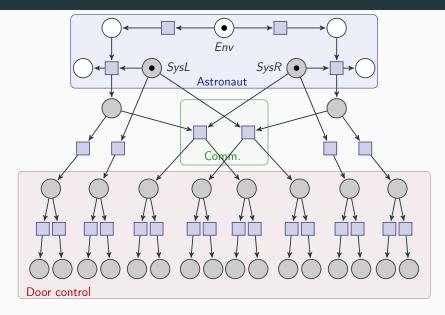
Memory Model of Petri Games: Causal Past



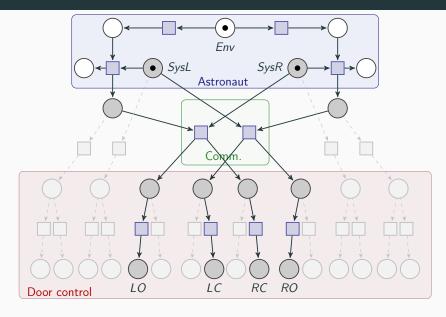
Refuse transitions based on Causal Past



Unfolding of Airlock



Winning Strategy of Airlock σ



Reachable Markings

$$\mathscr{R}(\mathscr{N}) = \{ M \subseteq \mathscr{P} \mid \exists t_1, ..., t_n \in \mathscr{T} : \exists M_1, ..., M_n \subseteq \mathscr{P} : \\ In[t_1 \rangle M_1 ... [t_n \rangle M_n = M \}$$

Winning Safety Condition

A system strategy σ is winning for the condition safety (\mathscr{B}) iff

$$\forall M \in \mathscr{R}(\mathscr{N}^{\sigma}) : \sigma[M] \cap \mathscr{B} = \emptyset.$$

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Winning Safety Condition

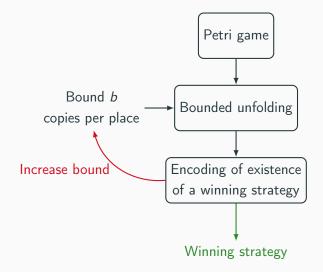
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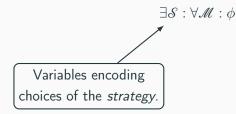
A Petri game $\mathcal G$ is winning iff there exists a winning strategy.

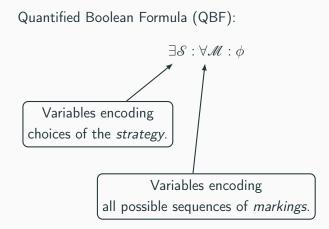
Bounded Synthesis

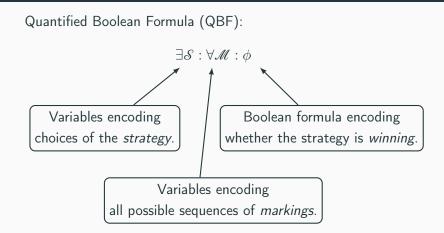
Bounded Synthesis for Petri Games

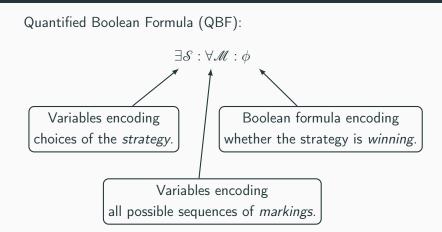


Quantified Boolean Formula (QBF):





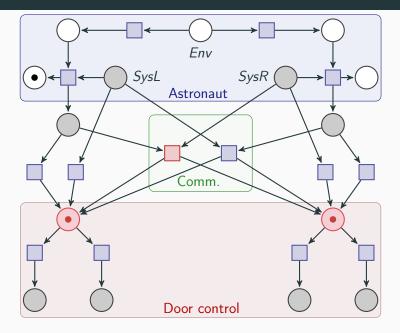




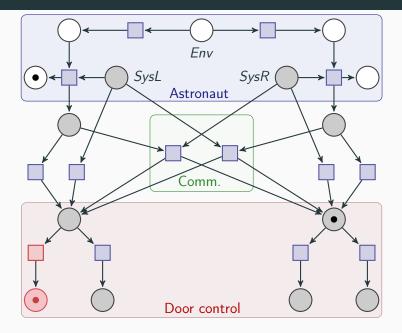
 $\phi = validStrategy \land validSequence \land terminating \land winningStrategy$

True Concurrency in Petri Games

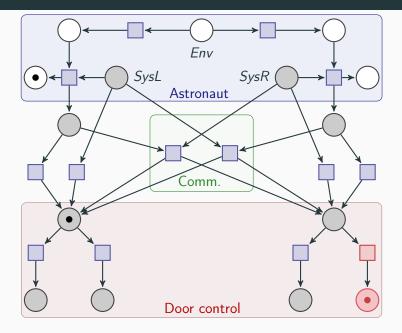
Which Player progresses Next?



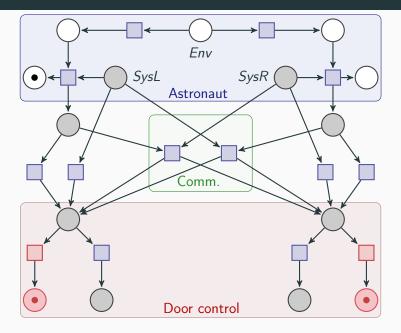
Left Door can be First

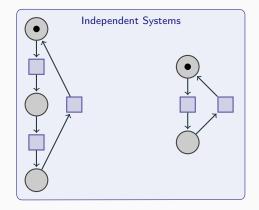


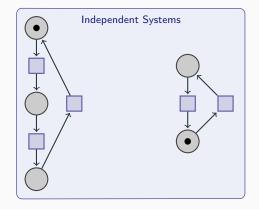
Right Door can be First

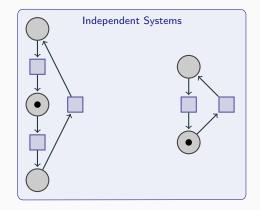


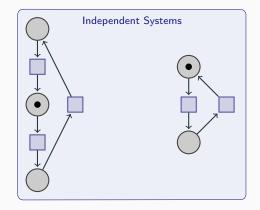
Both System Players

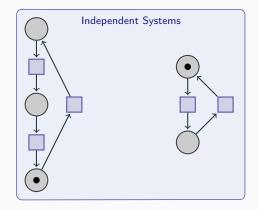


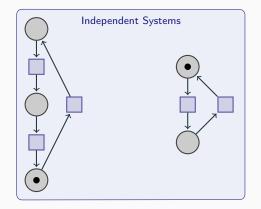




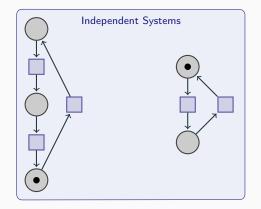




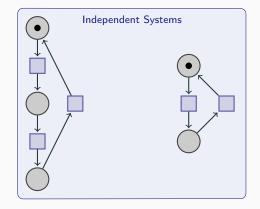


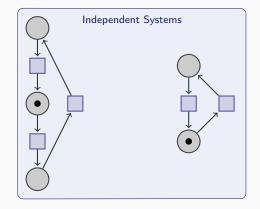


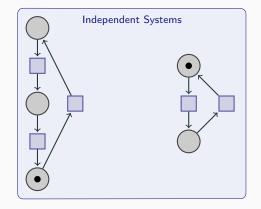
Many interleavings with same causal past!

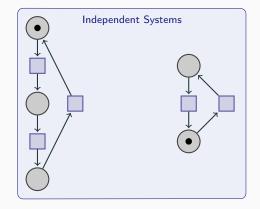


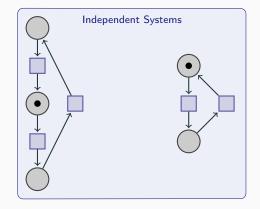
Many interleavings with same causal past! Fire all enabled transitions

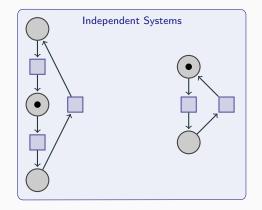






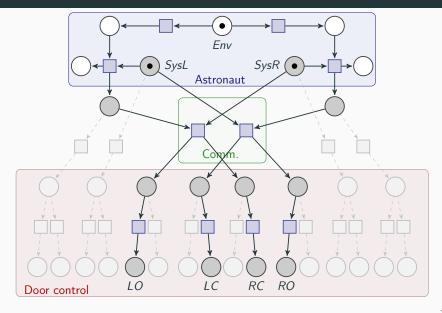




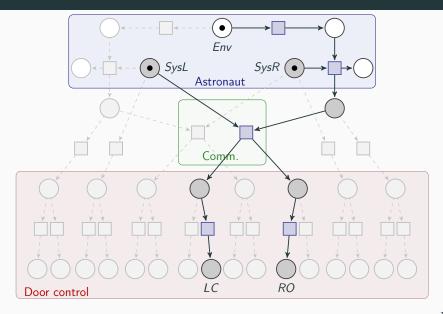


How to remain correct?

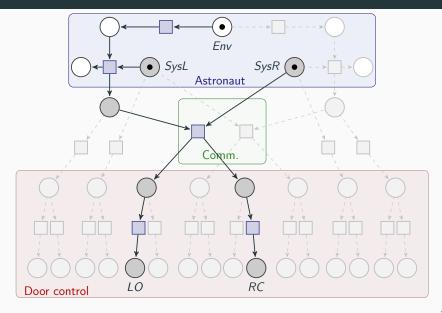
Environment Strategies for Airlock



Environment Strategies for Airlock



Environment Strategies for Airlock



Environment Strategy

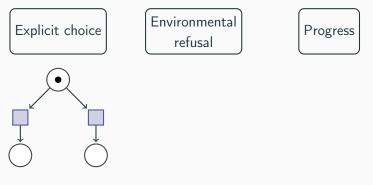
Definition

An environment strategy γ is a subnet of a system strategy σ that satisfies the conditions explicit choice, environmental refusal, and progress.

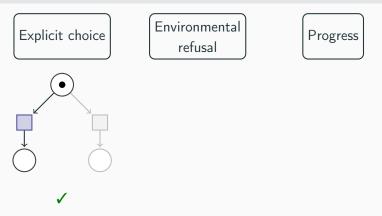
Environment Strategy

Definition

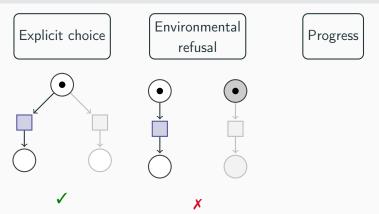
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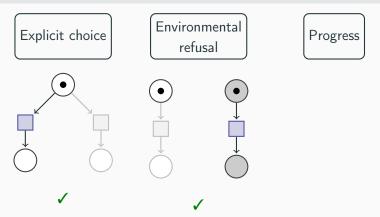
Definition



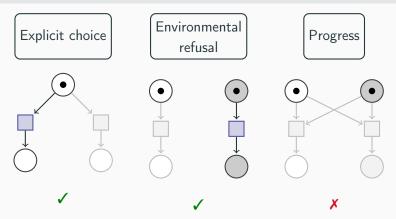
Definition



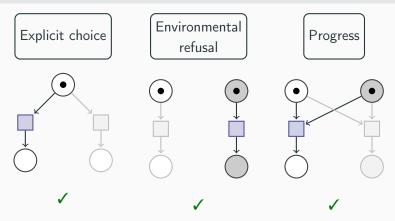
Definition



Definition



Definition

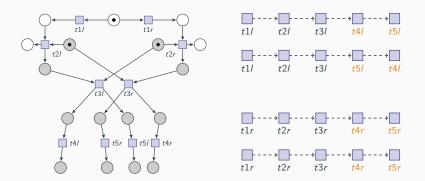


Theorem

An environment strategy γ leads to a *unique sequence* of fired transitions up to reordering of independent transitions.

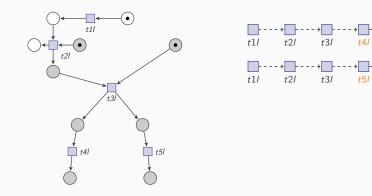
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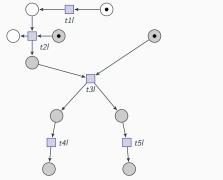


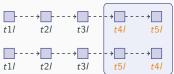
t5l

t4l

Theorem

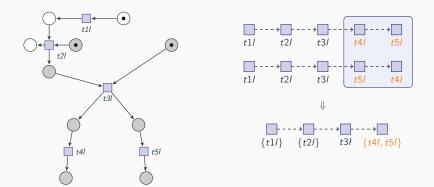
An environment strategy γ leads to a *unique sequence* of fired transitions up to reordering of independent transitions.





Theorem

An environment strategy γ leads to a *unique sequence* of fired transitions up to reordering of independent transitions.



$$\mathscr{R}^{seq}(\mathscr{N}) = \{ M \subseteq \mathscr{P} \mid \exists t_1, ..., t_n \in \mathscr{T} : \exists M_1, ..., M_n \subseteq \mathscr{P} : \\ In[t_1 \rangle M_1 ... [t_n \rangle M_n = M \}$$

 $\mathscr{R}^{tc}(\mathscr{N}) = \{ M \subseteq \mathscr{P} \mid \exists T_1, \dots, T_n \subseteq \mathscr{T} : \exists M_1, \dots, M_n \subseteq \mathscr{P} : \\ In[T_1 \rangle M_1 \dots [T_n \rangle M_n = M \}$

A system strategy σ is winning for the condition safety (\mathscr{B}) iff

$$\forall \boldsymbol{\gamma} : \forall \boldsymbol{M} \in \mathscr{R}(\mathscr{N}^{\sigma \boldsymbol{\gamma}}) : \sigma \boldsymbol{\gamma}[\boldsymbol{M}] \cap \mathscr{B} = \emptyset.$$

Theorem

$$\forall \gamma : \forall M \in \mathscr{R}^{tc}(\mathscr{N}^{\sigma\gamma}) : \sigma\gamma[M] \cap \mathscr{B} = \emptyset$$
$$\Leftrightarrow$$
$$\forall M \in \mathscr{R}^{seq}(\mathscr{N}^{\sigma}) : \sigma[M] \cap \mathscr{B} = \emptyset$$

Theorem

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$$\mathscr{R}^{\mathsf{seq}}(\mathscr{N}^{\sigma}) = \bigcup_{\gamma \in \mathscr{N}^{\sigma}} (\mathscr{R}^{\mathsf{seq}}(\mathscr{N}^{\sigma\gamma}))$$

Theorem

$$\begin{split} \forall \gamma : \forall M \in \mathscr{R}^{tc}(\mathscr{N}^{\sigma\gamma}) : \sigma\gamma[M] \cap \mathscr{B} = \emptyset \\ \Leftrightarrow \\ \forall M \in \mathscr{R}^{seq}(\mathscr{N}^{\sigma}) : \sigma[M] \cap \mathscr{B} = \emptyset \end{split}$$

$$egin{aligned} \mathscr{R}^{\mathsf{seq}}(\mathscr{N}^{\sigma}) &= igcup_{\gamma \in \mathscr{N}^{\sigma}}(\mathscr{R}^{\mathsf{seq}}(\mathscr{N}^{\sigma\gamma})) \ \mathscr{R}^{\mathsf{seq}}(\mathscr{N}^{\sigma}) \supseteq igcup_{\gamma \in \mathscr{N}^{\sigma}}(\mathscr{R}^{\mathsf{tc}}(\mathscr{N}^{\sigma\gamma})) \end{aligned}$$

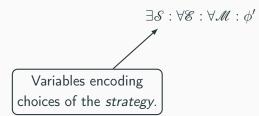
Theorem

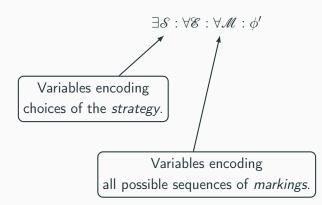
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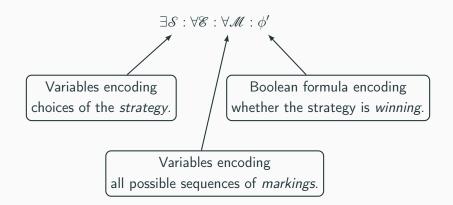
$$\mathcal{R}^{seq}(\mathcal{N}^{\sigma}) = \bigcup_{\gamma \in \mathcal{N}^{\sigma}} (\mathcal{R}^{seq}(\mathcal{N}^{\sigma\gamma}))$$
$$\mathcal{R}^{seq}(\mathcal{N}^{\sigma}) \supseteq \bigcup_{\gamma \in \mathcal{N}^{\sigma}} (\mathcal{R}^{tc}(\mathcal{N}^{\sigma\gamma}))$$
$$\bigcup_{M \in \mathcal{R}^{seq}(\mathcal{N}^{\sigma})} \bigcup_{p \in M} p = \bigcup_{M \in \bigcup_{\gamma \in \mathcal{N}^{\sigma}} (\mathcal{R}^{tc}(\mathcal{N}^{\sigma\gamma}))} \bigcup_{p \in M} p$$

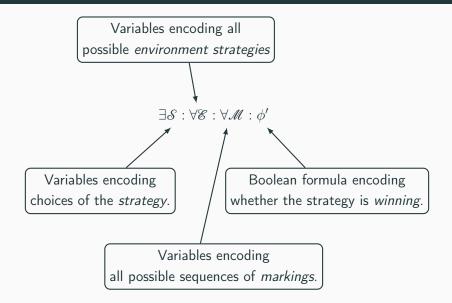
True Concurrency in Bounded Synthesis of Petri Games

$\exists \mathcal{S} : \forall \mathcal{E} : \forall \mathcal{M} : \phi'$









$\phi' = validEnvStrategy \Rightarrow$

(validStrategy \land validSequence \land terminating \land winningStrategy)

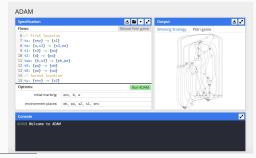
$\phi' = \textit{validEnvStrategy} \Rightarrow$

(validStrategy \land validSequence \land terminating \land winningStrategy)

validEnvStrategy: filters invalid environment strategiesvalidSequence: encodes true concurrent firing semanticsterminating: encodes termination of SCCs

Bounded Synthesis Implementation ADAM⁴

- Implementation of Petri game decision procedures
- Online interface for bounded synthesis
- Try it online: https://react.uni-saarland.de/ADAM

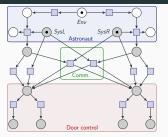


⁴Finkbeiner, Gieseking, and Olderog, "Adam: Causality-Based Synthesis of Distributed Systems".

Experimental Evaluation

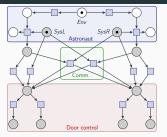
		Sequential		True Concurrent	
Benchmark	Parameter	Iteration	Runtime in seconds	Iteration	Runtime in seconds
Alarm System	2	7	13.26	6	11.15
	3	-	timeout	-	timeout
Collision Avoidance	2	8	7.27	5	6.25
	3	-	timeout	6	14.21
	4	-	timeout	7	346.23
	5	-	timeout	-	timeout
Disjoint Routing	2	8	6.16	7	6.05
	3	11	11.03	9	10.07
	4	14	69.50	11	65.31
	5	-	timeout	-	timeout
Production Line	1	4	5.59	4	5.59
	2	5	6.08	4	5.85
	5	8	87.33	4	41.95
	6	-	timeout	4	742.36
	7	-	timeout	-	timeout
Document Workflow	1	8	5.90	7	5.79
	2	10	6.58	9	6.44
	10	26	716.61	25	823.94
	11	28	1304.14	-	timeout
	12	-	timeout	-	timeout

Airlock as Petri Game



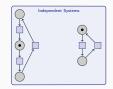
4

Airlock as Petri Game



True Concurrent Firing

4

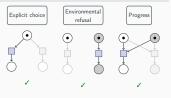


How to remain correctness?

Environment Strategy

Definition

An environment strategy γ is a subnet of a system strategy σ that satisfies the conditions explicit choice, environmental refusal, and progess.

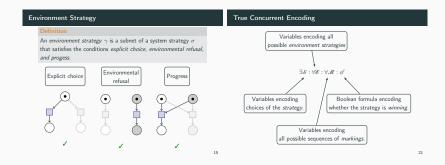


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True Concurrent Encoding Environment Strategy Definition Variables encoding all An environment strategy γ is a subnet of a system strategy σ possible environment strategies that satisfies the conditions explicit choice, environmental refusal, and progess. Environmental $\exists \mathcal{S}: \forall \mathcal{E}: \forall \mathcal{M}: \partial'$ Explicit choice Progress refusal • Variables encoding Boolean formula encoding • • . choices of the strategy. whether the strategy is winning. Variables encoding all possible sequences of markings. 1 1 1

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It is beneficial to implement asynchronicity as true concurrency in distributed synthesis!

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Known Decidability Classes of Petri Games

- 1 environment player, bounded system players \Rightarrow EXPTIME-complete⁵
- bounded environment players, 1 system player \Rightarrow EXPTIME-complete⁶
- Acyclic communication
 - $\Rightarrow \mathsf{Non-elementary}^7$

⁵Finkbeiner and Olderog, "Petri Games: Synthesis of Distributed Systems with Causal Memory".

⁶Finkbeiner and Gölz, "Synthesis in Distributed Environments".

⁷Beutner, Finkbeiner, and Hecking-Harbusch, "Translating Asynchronous Games for Distributed Synthesis".