

Module Checking

An overview by
Maël Hörz

Paper by

Orna Kupfermann, Moshe Y. Vardi, Pierre Wolper

Talk-Outline

- Closed Systems vs. Open Systems
- Transition Systems (Programs/Reactive Programs)
- Temporal Logic
- Module Checking
- Complexity of Module Checking

Introduction

- System Design
 - Closed systems vs. Open systems

Closed system

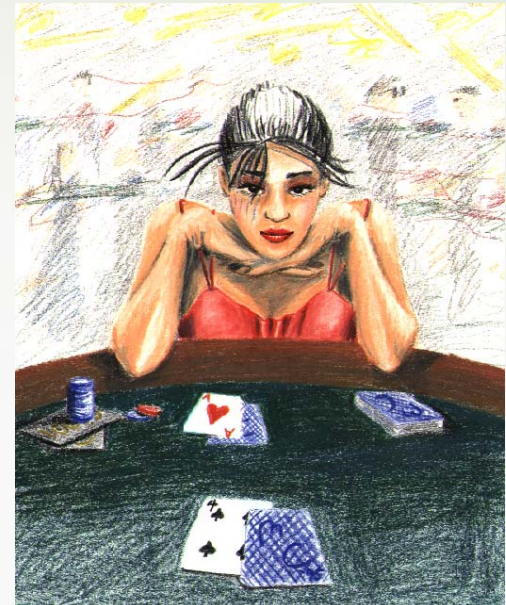
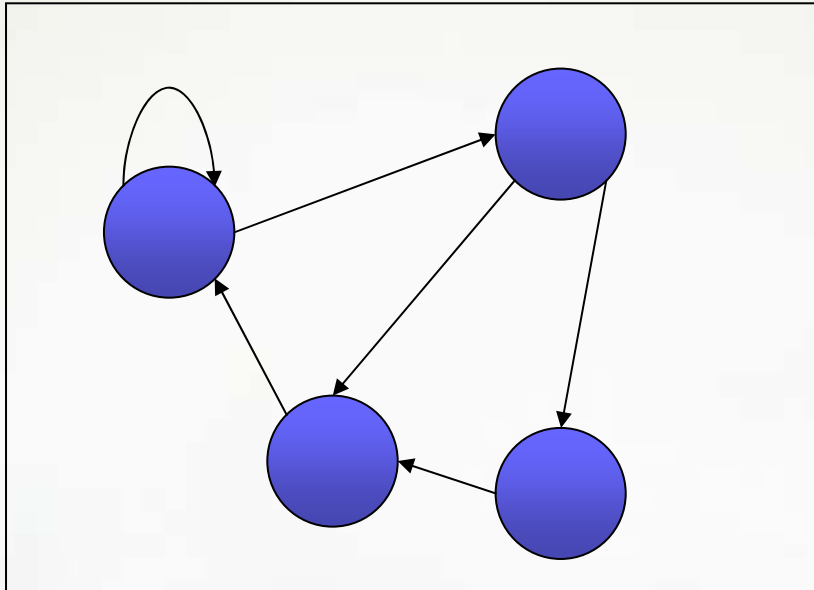
- Behavior
 - Completely determined by the state of the system
- One kind of non-determinism
 - Only internal

Open system

- Behavior
 - Depends on the interaction with its environment
- Two kinds of non-determinism
 - External (uncontrollable)
 - Internal (controllable)

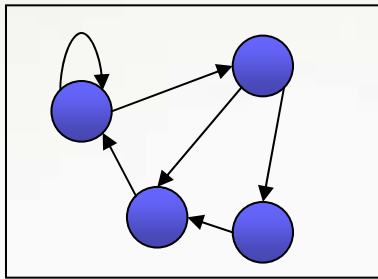
Closed system - One player

- System / Internal player (= only player)

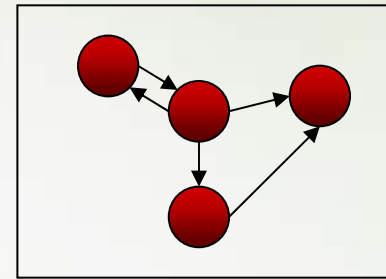


Open system - Two players

- System/ internal player
- controllable
- Environment / external player
- uncontrollable



Interaction



versus



No gambling

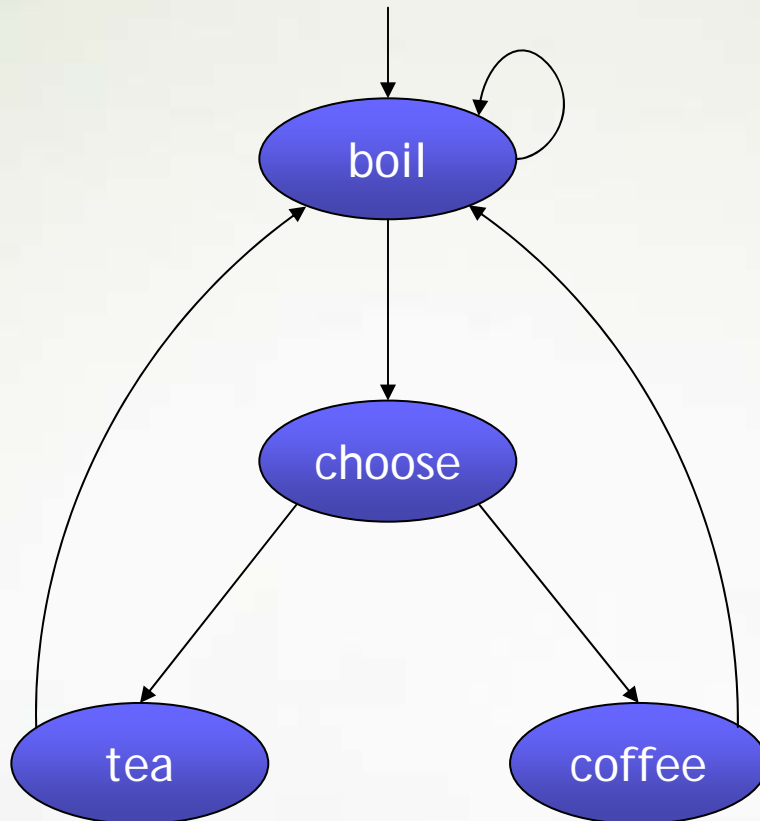
- We are only interested in safe systems



Introduction

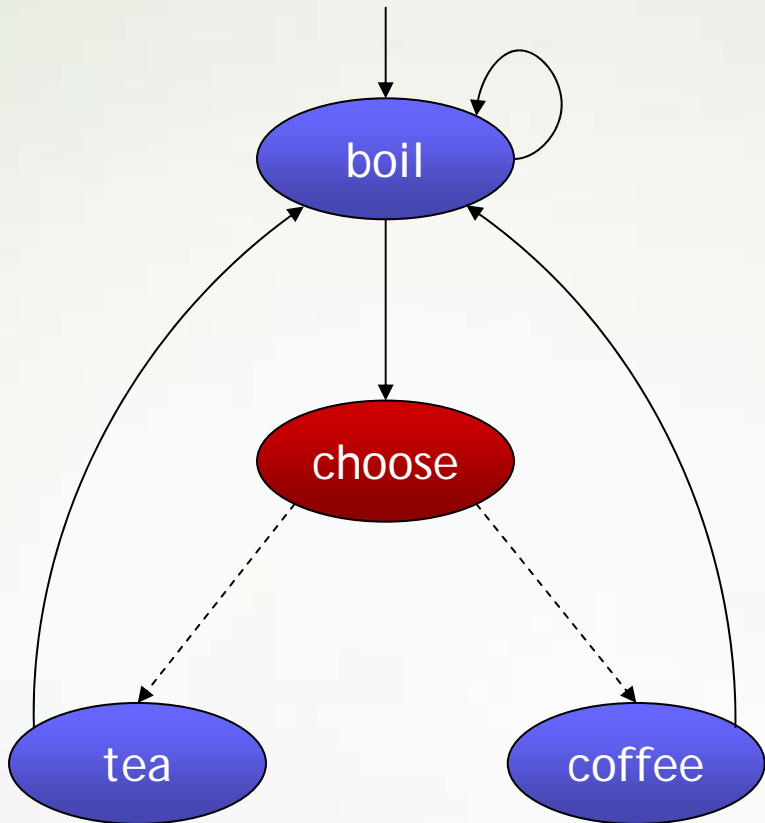
- Environment
 - Everything not under control of system itself
- Reactive system
 - Open system
 - Does not terminate
 - Interacts with an environment
- External vs. internal
 - Environment makes external choices
 - System makes internal choices

Example



- Closed system
 - Repeatedly boils water
 - Makes internal non-det. choice
 - Serves either tea or coffee
 - One player:
machine

Example



- Open system
 - Repeatedly boils water
 - Asks environment to choose between coffee and tea
 - Serves a drink according to the external choice
 - Two players:
machine vs. **user**
 - Controllability of non-det. depends on player

Model vs. Module Checking

- Verification of closed systems
 - Model checking:
 - machine has to satisfy given requirements
- Verification of **open** systems:
 - **Module checking**
 - **For all env.:** machine has to satisfy given requirements
 - “Model checking of open systems”

Model/Module Checking

- General idea of model/module checking
 - Express design as a formal model M
 - Finite state transition system
 - Specify required behavior with a logic formula ψ
 - Check that M satisfies ψ

Transition Systems

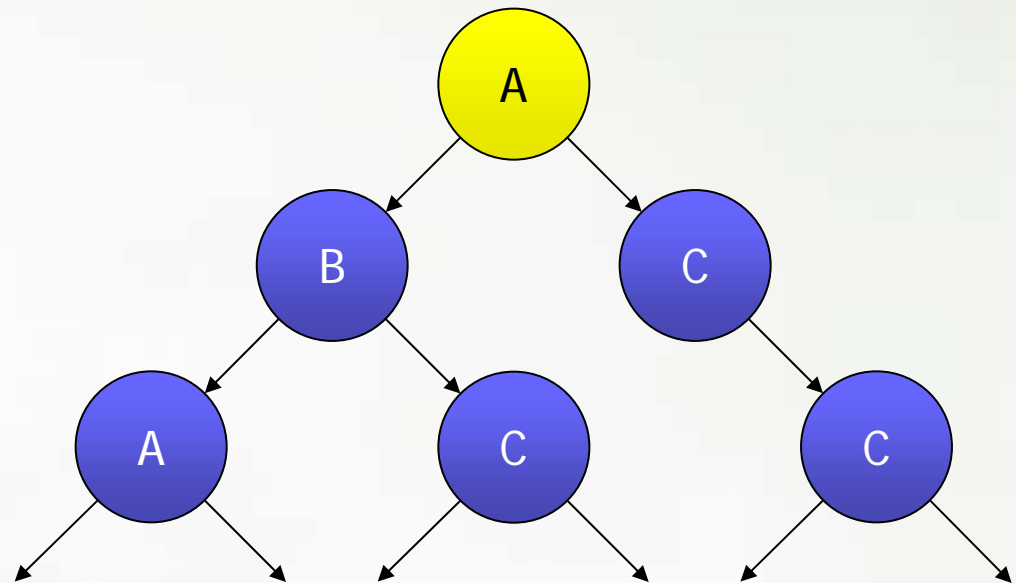
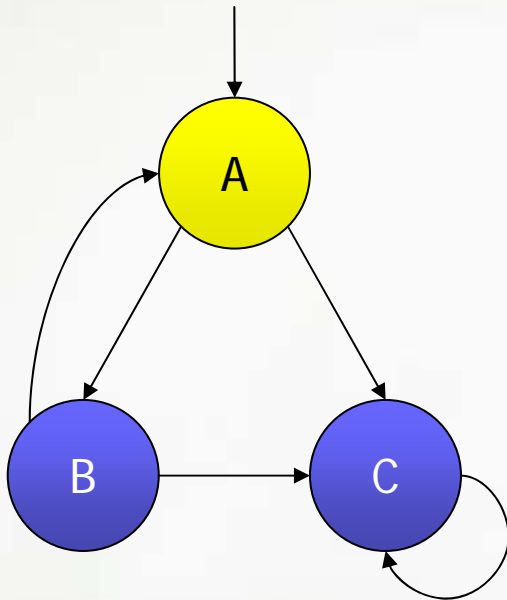
- Program $P = (AP, W, R, w_0, L)$
 - AP : set of atomic propositions
 - W : set of states
 - $R \subseteq W \times W$: transition relation (must be total)
 - w_0 : an initial state
 - $L:W \rightarrow 2^{AP}$: maps each state to a set of atomic propositions true in this state
- Atomic propositions
 - The state of a variable, e.g. $x = 5$ and $y = 7$ always holds in state s , then $L(s) = \{x = 5, y = 7\}$
 - In state "tea" it holds that tea is served

Transition Systems

- Module $M = (AP, W_s, W_e, R, w_0, L)$
 - AP : set of atomic propositions
 - W_s, W_e : set of system/environment states
 - $W = W_s \cup W_e$
 - $R \subseteq W \times W$: transition relation (must be total)
 - w_0 : an initial state
 - $L: W \rightarrow 2^{AP}$: maps each state to a set of atomic propositions true in this state

TS and its unwinding

- Transition System
- Unwinding of TS (Infinite execution tree)
 - Every path represents a possible execution



Temporal Logics

- Reactive systems do not terminate
 - \Rightarrow We get infinite execution trees
 - \Rightarrow No end state where we can check requirements
 - \Rightarrow Want to check properties **while** execution
 - \Rightarrow Need to express temporal aspects in requirements

LTL - Linear Temporal Logic

- Syntax

$$\varphi ::= true \mid a \mid \varphi_1 \wedge \varphi_2 \mid \neg \varphi \mid X\varphi \mid F\varphi \mid G\varphi \mid \varphi_1 \cup \varphi_2$$

where $a \in AP$

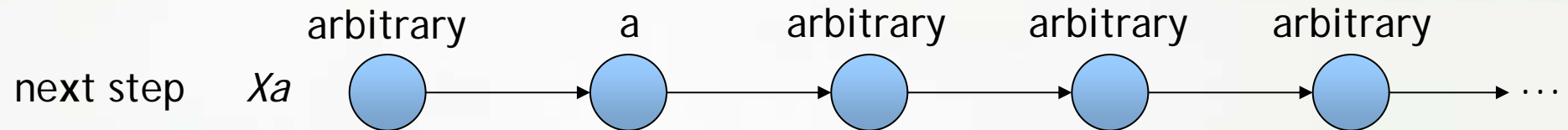
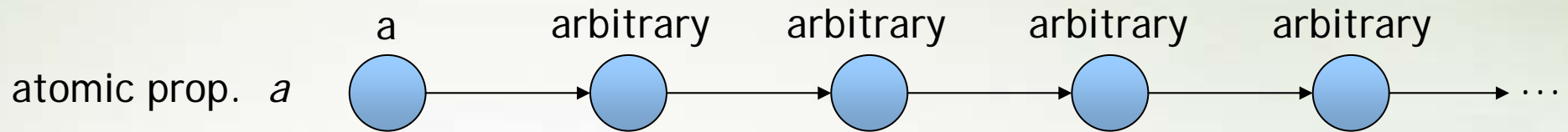
- Formula composed of

- Atomic propositions
- Boolean connectors
- Temporal operators

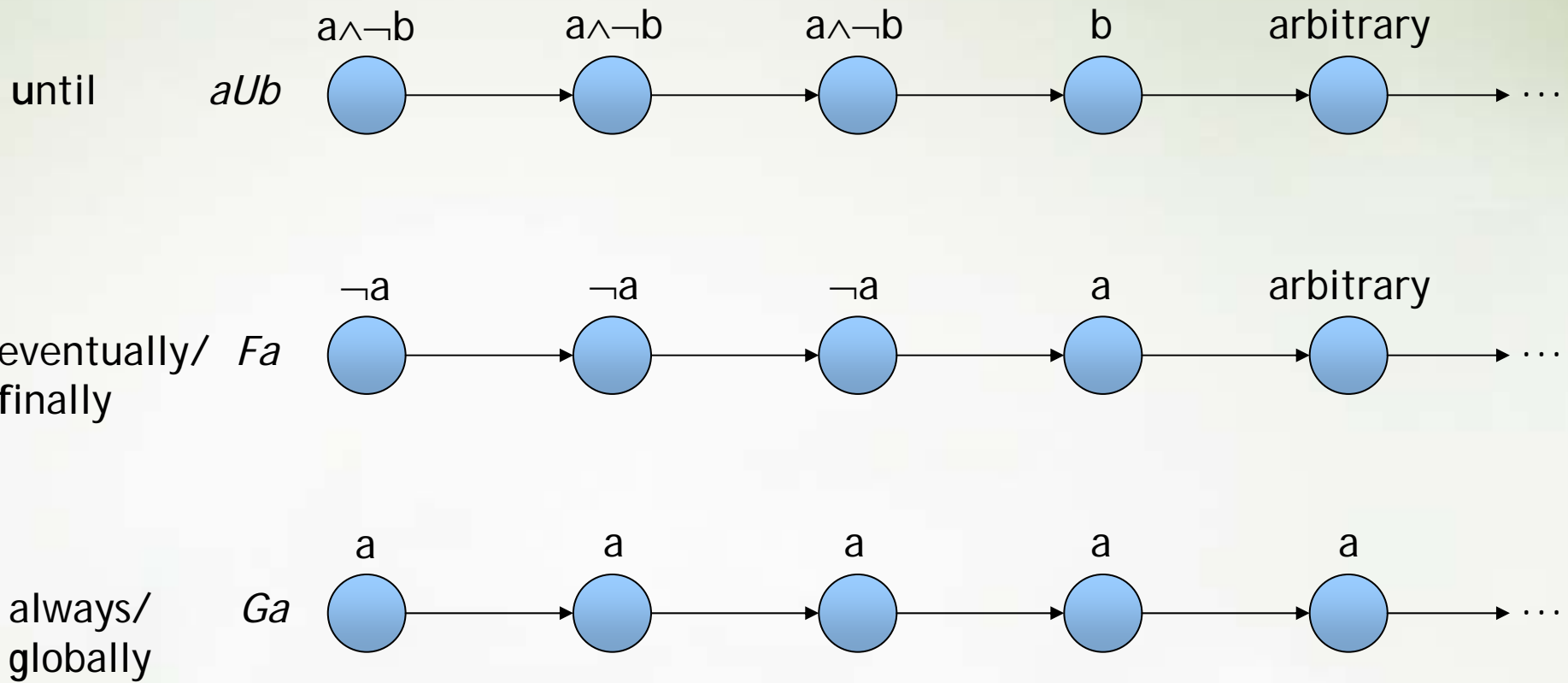
- Using \wedge and \neg the remaining connectives \vee , \oplus , \rightarrow , \leftrightarrow , *nor*, *nand* can be derived

- Similarly, F and G could be derived from the U operator

LTL- Intuitive Semantics (1/2)



LTL- Intuitive Semantics (2/2)



CTL - Computational Tree Logic

- State-formulas

$$\Phi ::= true \mid a \mid \Phi_1 \wedge \Phi_2 \mid \neg\Phi \mid \exists\varphi \mid \forall\varphi$$

where $a \in AP$ and φ is a path-formula

- State formulas express a property of a state

- Path-formulas

$$\varphi ::= X\Phi \mid F\Phi \mid G\Phi \mid \Phi_1 \cup \Phi_2$$

where Φ, Φ_1, Φ_2 are state-formulas

- Path formulas express a property of a path
 - Path = infinite sequence of states

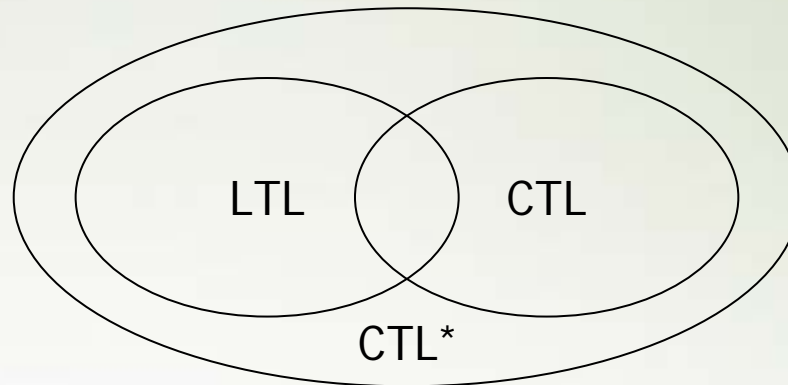
CTL - Semantics

- Temporal operators X, F, G, U have analog semantics to their LTL-semantics
- **New: Path-quantifiers**
 - Let φ be a path-formula
 - Universal path quantifier
 - $\forall\varphi$: φ has to hold on all paths
 - Existential path quantifier $\exists\varphi$
 - $\exists\varphi$: φ has to hold on at least one path
- **CTL***
 - Like CTL, but temporal operators can be freely mixed

Comparison of LTL, CTL, CTL*

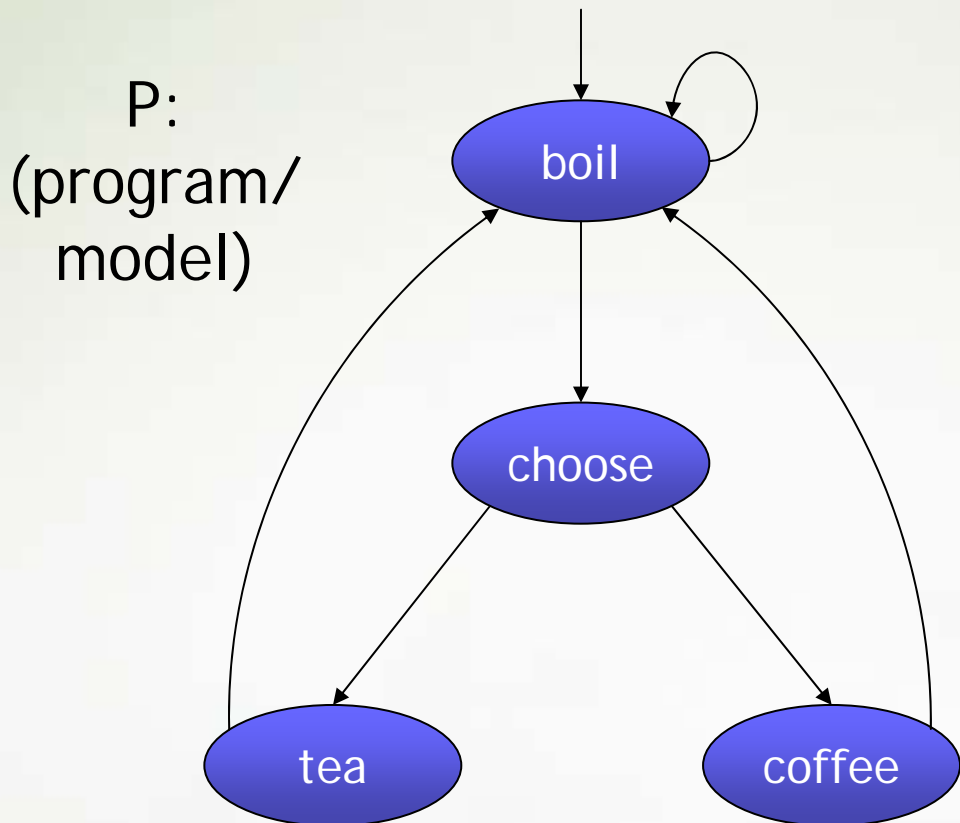
- CTL vs. CTL*
 - CTL: one path operator followed by a state operator
 - CTL*: temporal operators can be freely mixed
- LTL expressed in CTL*
 - LTL-formula checked on all paths of TS
⇒ implicit \forall -quantification
 - LTL formula φ expressed as CTL* formula $\forall\varphi$

Expressiveness of LTL, CTL, CTL*



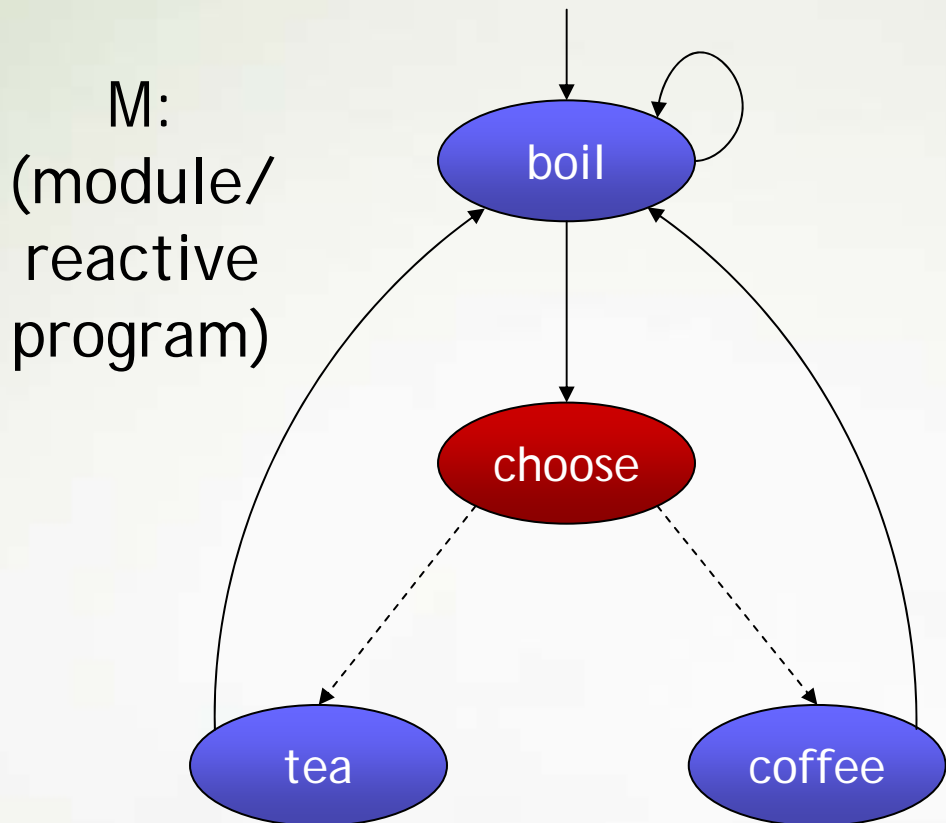
- $LTL \not\subseteq CTL$
 - $FGa \in LTL$ but $FGa \notin CTL$ (idea: $\forall F \forall Ga \neq \forall FGa$)
- $CTL \not\subseteq LTL$
 - $\forall G \exists F \in CTL$ but $\forall G \exists F \notin LTL$ (idea: no \exists in LTL)
- $LTL \subset CTL^*$
 - Add \forall in front of LTL formula
- $CTL \subset CTL^*$
 - CTL^* is an extension of CTL

Model Checking vs. Module Checking



- Model checking
- Is it always possible to eventually serve tea?
- Does $P \models \forall G \exists F \text{ tea}$ hold?
- Yes
 - System controls non-determinism of “choose”

Model Checking vs. Module Checking



- Module checking
- Is it always possible to eventually serve tea?
- Does $M \models \forall G \exists F \text{ tea}$ hold?
- No
 - Environment controls non-determinism of choose
 - If environment chooses always coffee \Rightarrow M can never serve tea

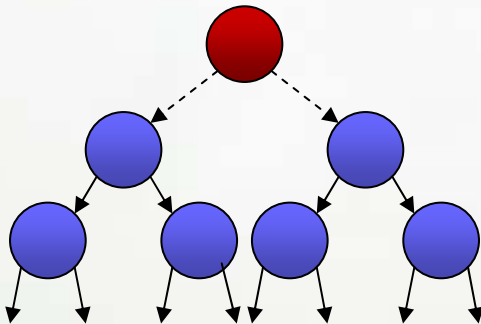
Model Checking vs. Module Checking

- Model checking tools will always answer yes
 - M is regarded as program (no environment)
 - \Rightarrow wrong answer for modules
 - Adapt model checking tools such that module checking works

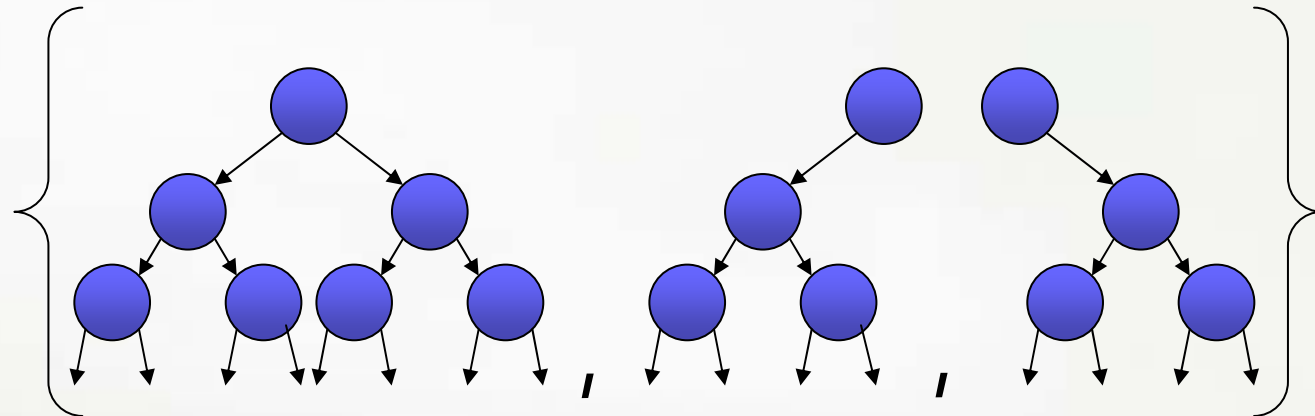
Module Checking

- Execution tree
 - Tree obtained from unrolling program/module
- In module checking set of execution trees, $exec(M)$
- $exec(M)$
 - Let ET be the execution tree
 - By pruning from ET sub-trees, which have as root node a successor of an **environment node**, we obtain $exec(M)$.

Execution tree of M :



$exec(M)$:



Module Checking

- Intuitively
 - Each tree in $exec(M)$ corresponds to a different behavior of the environment
- Module checking
 - Given module M , CTL* formula ψ
 - $M \models_r \psi$, if all trees in $exec(M)$ satisfy ψ
 - I.e. apply model checking to all trees in $exec(M)$
- Module checking can be solved using non-det. tree automata

Complexity

- $\forall\text{CTL}^*$, $\forall\text{CTL}$
 - CTL^*/CTL restricted to \forall -quantification
- Module checking problem for $\forall\text{CTL}^*$
 - Theorem
 - Coincides with model checking problem for $\forall\text{CTL}^*$
 - Proof idea
 - All choices have to be considered since no \exists -quantification
 - No difference between system and environment non-determinism
 - Module/model checking of LTL , $\forall\text{CTL}$, $\forall\text{CTL}^*$ of same complexity
 - Since LTL , $\forall\text{CTL}$ are subsets of $\forall\text{CTL}^*$

Complexity

- Results
 - Module checking for \forall CTL is in linear time
 - Module checking problem for LTL, \forall CTL* is PSPACE-complete
 - Program complexity of module checking for LTL, \forall CTL, \forall CTL* is NLOGSPACE-complete

Complexity

- Module checking problem for CTL
 - EXPTIME-complete
- Module checking problem for CTL*
 - 2EXPTIME-complete
- Proof idea
 - Model checking problem for CTL is in linear-time
 - Module checking of model M runs model-checking on all trees in $\text{exec}(M)$
 - $\text{exec}(M)$ is a subset of the power set of M , i.e. we get an exponential blow-up

Complexity

- Is it really that bad?
- Good news
 - Model checking tools can be easily adjusted for commonly-used fragment of CTL
 - Module checking problem for $\exists F\xi$ and $\forall G\exists F\xi$ in linear time
 - Program-complexity of module checking for $\exists F\xi$ and for $\forall G\exists F\xi$ is PTIME-complete

Complexity-Overview

	Model checking	Module checking	Program complexity of model checking	Program complexity of module checking
LTL	PSPACE	PSPACE	NLOGSPACE	NLOGSPACE
CTL	linear-time	EXPTIME	NLOGSPACE	PTIME
CTL*	PSPACE	2EXPTIME	NLOGSPACE	PTIME
\forall CTL	linear-time	linear-time	NLOGSPACE	NLOGSPACE
\exists CTL	linear-time	EXPTIME	NLOGSPACE	PTIME
$\exists F \xi$ $\forall G \exists F \xi$	linear-time	linear-time	NLOGSPACE	PTIME

Summary

- Closed systems vs. Open system
 - Closed system
 - No interaction, total control
 - Open systems interact with an environment
 - “Game between system and environment player”
- Temporal logic formulas to specify requirements
 - Want to check properties **while** execution
- Module checking
 - $M \vDash_r \psi$
 - Module M has to satisfy ψ in all environments
- Module checking is much more complex than model checking
- Commonly used subset of CTL has linear complexity

References

- “Module Checking”
by Orna Kupferman, Moshe Y. Vardi, Pierre Wolper
- “Principles of Model Checking”
by Christel Baier and Joost-Pieter Katoen
- Pictures in introduction from various sources