



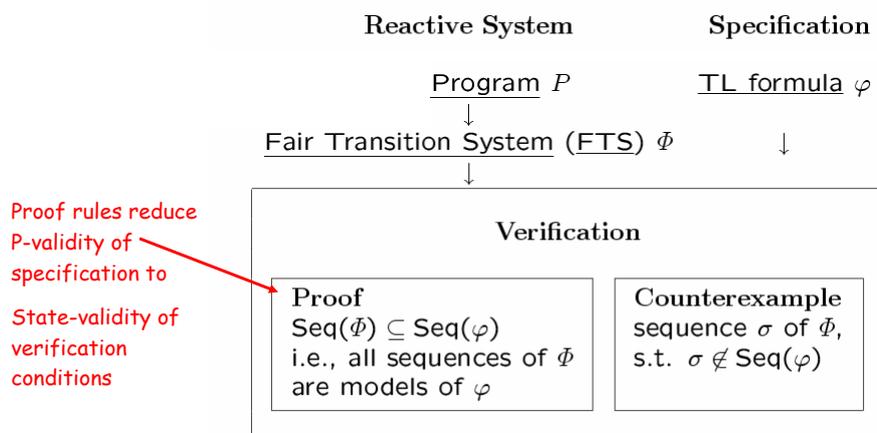
Verification - Lecture 4

Proving Invariance Properties II

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Big Picture



Proving Invariance

Review

For assertion q ,

$$\text{B1. } P \models \Theta \rightarrow q$$

$$\text{B2. } P \models \{q\} \mathcal{T} \{q\}$$

$$P \models \Box q$$

B-INV

- for $\tau \in \mathcal{T}$ in P
 $\{\varphi\}\tau\{\psi\}$: $\rho_\tau \wedge \varphi \rightarrow \psi'$
"τ leads from φ to ψ in P "
- for \mathcal{T} in P
 $\{\varphi\}\mathcal{T}\{\psi\}$: $\{\varphi\}\tau\{\psi\}$ for every $\tau \in \mathcal{T}$
"T leads from φ to ψ in P "

Review: Runs

Review

Infinite sequence of states

$$\sigma: s_0, s_1, s_2, \dots$$

is a **run** of a transition system, if it satisfies the following:

- Initiality: s_0 satisfies θ
- Consecution: For each $i = 0, 1, \dots$

there is a transition $\tau \in \mathcal{T}$ s.t. $s_{i+1} \in \tau(s_i)$

Example: REQUEST-RELEASE

Review

local x : integer where $x = 1$

$$\left[\begin{array}{l} \ell_0 : \text{request } x \\ \ell_1 : \text{critical} \\ \ell_2 : \text{release } x \\ \ell_3 : \end{array} \right]$$

$$P \models \square \underbrace{x \geq 0}_q$$

$$\Theta: x = 1 \wedge \pi = \{\ell_0\}$$

$$\mathcal{T}: \{\tau_I, \tau_{\ell_0}, \tau_{\ell_1}, \tau_{\ell_2}\}$$

Example: REQUEST-RELEASE

Review

$$\text{B1: } \underbrace{x = 1 \wedge \pi = \{\ell_0\}}_{\Theta} \rightarrow \underbrace{x \geq 0}_q$$

B2:

$$\tau_I: \underbrace{x \geq 0}_q \wedge \underbrace{x' = x \wedge \pi' = \pi}_{\rho_{\tau_I}} \rightarrow \underbrace{x' \geq 0}_{q'}$$

$$\tau_{\ell_0}: \underbrace{x \geq 0}_q \wedge \underbrace{\text{move}(\ell_0, \ell_1) \wedge x > 0 \wedge x' = x - 1}_{\rho_{\tau_{\ell_0}}} \rightarrow \underbrace{x' \geq 0}_{q'}$$

$$\tau_{\ell_1}: \underbrace{x \geq 0}_q \wedge \underbrace{\text{move}(\ell_1, \ell_2) \wedge x' = x}_{\rho_{\tau_{\ell_1}}} \rightarrow \underbrace{x' \geq 0}_{q'}$$

$$\tau_{\ell_2}: \underbrace{x \geq 0}_q \wedge \underbrace{\text{move}(\ell_2, \ell_3) \wedge x' = x + 1}_{\rho_{\tau_{\ell_2}}} \rightarrow \underbrace{x' \geq 0}_{q'}$$

Example: REQUEST-RELEASE

Review

local x : integer where $x = 1$

$$\left[\begin{array}{l} \ell_0 : \text{request } x \\ \ell_1 : \text{critical} \\ \ell_2 : \text{release } x \\ \ell_3 : \end{array} \right]$$

$$P \models \square \underbrace{x \geq 0}_q \quad \checkmark$$

Let's try

$$P \models \square \underbrace{(at_l_1 \rightarrow x = 0)}_q$$

Attempt #1

Review

$$\mathbf{B1:} \underbrace{x = 1 \wedge \pi = \{\ell_0\}}_{\Theta} \rightarrow \underbrace{at_l_1 \rightarrow x = 0}_q$$

holds since $\pi = \{\ell_0\} \rightarrow at_l_1 = \text{F}$

$$\mathbf{B2:} \{q\} \tau_{\ell_0} \{q\}$$

$$\underbrace{at_l_1 \rightarrow x = 0}_q \wedge \underbrace{move(\ell_0, \ell_1) \wedge x > 0 \wedge x' = x - 1}_{\rho \tau_{\ell_0}}$$

$$\rightarrow \underbrace{at'_l_1 \rightarrow x' = 0}_{q'}$$

we have $move(\ell_0, \ell_1) \rightarrow at'_l_1 = \text{T}$

BUT

$$(at_l_1 \rightarrow x = 0) \wedge x > 0 \wedge x' = x - 1 \rightarrow x' = 0$$

Cannot prove: not state-valid

Inductive Assertions

Review

For assertion q ,

$$\text{B1. } P \models \theta \rightarrow q$$

$$\text{B2. } P \models \{q\} \mathcal{T} \{q\}$$

$$P \models \Box q$$

B-INV

- q is inductive if B1 and B2 are (state) valid
- By rule B-INV,
every inductive assertion q is P -invariant
- The converse is not true

Example: REQUEST-RELEASE

Review

$$P \models \Box \underbrace{(at_l_1 \rightarrow x = 0)}_q$$

q is not inductive.

$$\text{B2: } \{q\} \tau_{\ell_0} \{q\}$$

$$\underbrace{at_l_1 \rightarrow x = 0}_q \wedge \underbrace{move(\ell_0, \ell_1) \wedge x > 0 \wedge x' = x - 1}_{\rho \tau_{\ell_0}}$$

$$\rightarrow \underbrace{at'_l_1 \rightarrow x' = 0}_{q'}$$

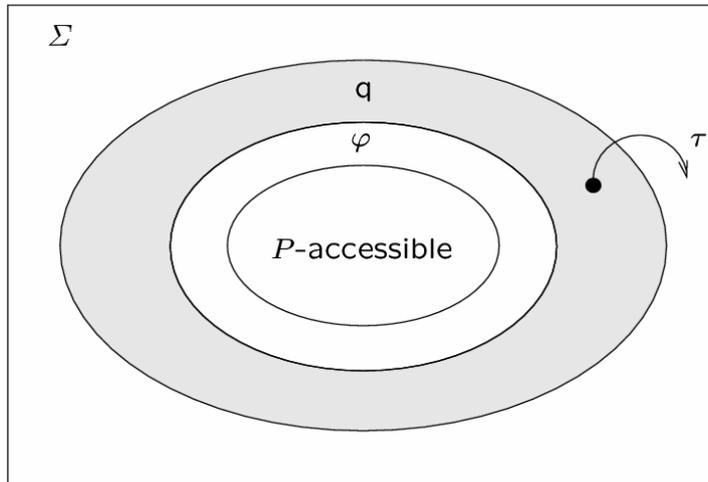
is not state valid, but it is P -state valid.

Two strategies:

1. Strengthening
2. Incremental Proofs

Strategy 1: Strengthening

Review



Find a stronger assertion φ that is inductive and implies the assertion q we want to prove.

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Rules

Review

For assertions q_1, q_2 ,

$$\frac{P \models \Box q_1 \quad P \models q_1 \rightarrow q_2}{P \models \Box q_2}$$

MON-I

For assertions q, φ

$$\begin{array}{l} \text{I1. } P \models \varphi \rightarrow q \\ \text{I2. } P \models \Theta \rightarrow \varphi \\ \text{I3. } P \models \{\varphi\} \mathcal{T} \{\varphi\} \\ \hline P \models \Box q \end{array}$$

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Example: REQUEST-RELEASE

Review

local x : integer where $x = 1$

$$P \models \square \underbrace{(at_l_1 \rightarrow x = 0)}_q$$

$$\left[\begin{array}{l} l_0 : \text{request } x \\ l_1 : \text{critical} \\ l_2 : \text{release } x \\ l_3 : \end{array} \right]$$

inductive assertion that implies

$$q : at_l_1 \rightarrow x = 0$$

is

$$\varphi : (at_l_1 \rightarrow x = 0) \wedge (at_l_0 \rightarrow x = 1)$$

Example (cont'd)

Review

Consider $\{\varphi\} \tau_{l_0} \{\varphi'\}$:

$$\underbrace{(at_l_0 \rightarrow x = 1) \wedge (at_l_1 \rightarrow x = 0)}_{\varphi} \wedge$$

$$\underbrace{move(l_0, l_1) \wedge x > 0 \wedge x' = x - 1}_{\rho_{\tau_{l_0}}}$$

$$\rightarrow \underbrace{(at_l'_0 \rightarrow x' = 1) \wedge (at_l'_1 \rightarrow x' = 0)}_{\varphi'}$$

$move(l_0, l_1)$ implies $l_0 \in \pi, l_0 \notin \pi', l_1 \in \pi'$

Therefore

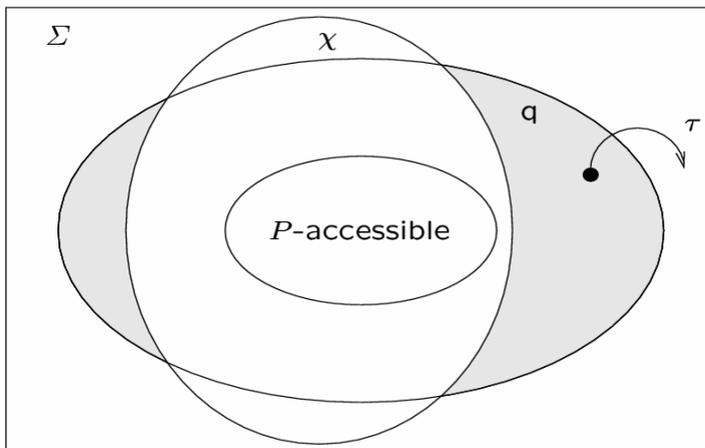
$$(T \rightarrow x = 1) \wedge \dots \wedge x' = x - 1 \wedge x > 0$$

$$\rightarrow (F \rightarrow \dots) \wedge (T \rightarrow x' = 0)$$

holds.

Strategy 2: Incremental Proofs

Review



Use previously proven invariances χ to exclude parts of the state space from consideration.

Rules

Review

For assertions q_1, q_2 and χ ,

$$P \models \Box \chi$$

$$\models \chi \wedge q_1 \rightarrow q_2$$

$$P \models \Box(q_1 \rightarrow q_2)$$

SV-PSV

For assertions q_1 and q_2 ,

$$P \models \Box q_1$$

$$P \models \Box q_2$$

$$P \models \Box(q_1 \wedge q_2)$$

I-CON

Combining the Strategies

Review

For assertions $q, \varphi, \chi_1, \dots, \chi_k$

$$\text{I0. } P \models \Box \chi_1, \dots, \Box \chi_k$$

$$\text{I1. } P \models \left(\bigwedge_{i=1}^k \chi_i \right) \wedge \varphi \rightarrow q$$

$$\text{I2. } P \models \Theta \rightarrow \varphi$$

$$\text{I3. } P \models \left\{ \left(\bigwedge_{i=1}^k \chi_i \right) \wedge \varphi \right\} \mathcal{T} \{ \varphi \}$$

$$P \models \Box q$$

INC-INV

Finding Inductive Invariants

Review

Construction of inductive assertions by

1. Bottom-up methods:

- Based on program text only
- Algorithmic
- Guaranteed to produce an inductive invariant

2. Top-down methods:

- Guided by the property we want to prove
- Heuristic
- Not guaranteed to produce an inductive invariant

Top-Down Approach

Review

previously proven $\Box \chi$

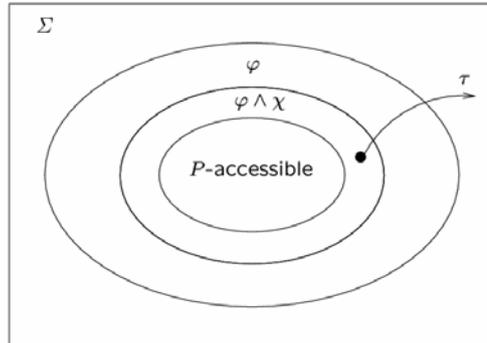
want to prove $\Box \varphi$

but

$$\{\chi \wedge \varphi\} \tau \{\varphi\}$$

not state-valid

for some $\tau \in \mathcal{T}$.

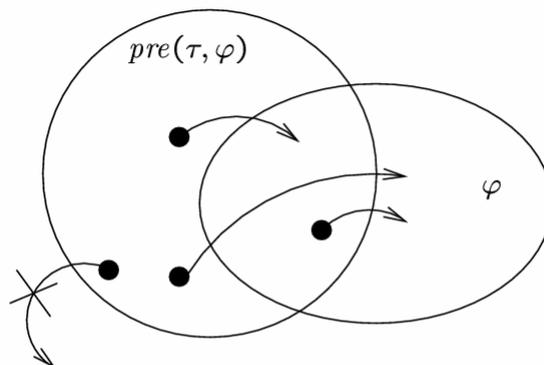


Solution: Take the largest set of states that will result in a φ -state when τ is taken.

Precondition

Review

$$pre(\tau, \varphi) : \forall V'. \rho_{\tau} \rightarrow \varphi'$$



a state s satisfies $pre(\tau, \varphi)$

iff

all τ -successors of s satisfy φ .

Example

Review

$$V : \{x\}$$

$$\rho_\tau : x > 0 \wedge x' = x - 1$$

$$\varphi : x \geq 2$$

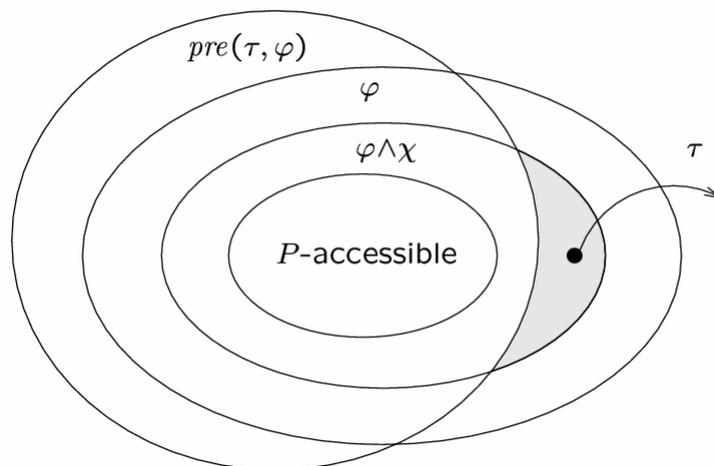
$$pre(\tau, \varphi) :$$

$$\forall x'. \underbrace{x > 0 \wedge x' = x - 1}_{\rho_\tau} \rightarrow \underbrace{x' \geq 2}_{\varphi'}$$

$$x > 0 \rightarrow x - 1 \geq 2$$

$$x \leq 0 \vee x \geq 3$$

Properties of Precondition



$\{\chi \wedge \varphi \wedge pre(\tau, \varphi)\} \tau \{\varphi\}$
is guaranteed to be state-valid.

Properties of Precondition

Claim: If φ is P -invariant then so is $pre(\tau, \varphi)$ for every $\tau \in \mathcal{T}$.

Proof:

Suppose φ is P -invariant, but $pre(\tau, \varphi)$ is not P -invariant.

Then there exists a P -accessible state s such that $s \not\models pre(\tau, \varphi)$.

But then, by the definition of $pre(\tau, \varphi)$, there exists a τ -successor s' of s such that $s' \not\models \varphi$.

Since s is P -accessible, s' is also P -accessible, contradicting that φ is a P -invariant.

Properties of Precondition

Definition: A transition τ is said to be self-disabling if for every state s , τ is disabled in all τ -successors of s .

Claim: For every assertion φ and self-disabling transition τ

$$\{\varphi \wedge pre(\tau, \varphi)\} \tau \{\varphi \wedge pre(\tau, \varphi)\}$$
is state-valid.

Proof

Assume $s \models \varphi \wedge pre(\tau, \varphi)$.

Then by definition of $pre(\tau, \varphi)$,
 $s' \models \varphi$.

Since τ is self-disabling, τ is disabled in all
 τ -successors s' of s , and so trivially
 $s' \models pre(\tau, \varphi)$

Thus for all τ -successors s' of s ,
 $s' \models \varphi \wedge pre(\tau, \varphi)$.

Heuristic

If the verification condition

$$\{\chi \wedge \varphi\} \tau \{\varphi\}$$

is not state-valid

- Strengthening approach:
strengthen φ by adding the conjunct $pre(\tau, \varphi)$
- Incremental approach:
prove $\Box pre(\tau, \varphi)$ and add $pre(\tau, \varphi)$ to χ .

Example

local x : integer where $x = 1$

$$\left[\begin{array}{l} \ell_0 : \text{request } x \\ \ell_1 : \text{critical} \\ \ell_2 : \text{release } x \end{array} \right]$$

$$\square \underbrace{(at_l_1 \rightarrow x = 0)}_{\varphi}$$

Problem:

$\{at_l_1 \rightarrow x = 1\} \tau_{\ell_0} \{at_l_1 \rightarrow x = 1\}$
is not state-valid.

If we use the above heuristic we get

$pre(\tau_{\ell_0}, \varphi) =$

$$\forall x', \pi'. \underbrace{(move(\ell_0, \ell_1) \wedge x > 0 \wedge x' = x - 1)}_{\rho_{\ell_0}} \rightarrow \underbrace{(at'_l_1 \rightarrow x' = 0)}_{\varphi}$$

Example (cont'd)

$pre(\tau_{\ell_0}, \varphi) =$

$$\forall x', \pi'. \underbrace{(move(\ell_0, \ell_1) \wedge x > 0 \wedge x' = x - 1)}_{\rho_{\ell_0}} \rightarrow \underbrace{(at'_l_1 \rightarrow x' = 0)}_{\varphi}$$

Since

$$move(\ell_0, \ell_1) \rightarrow at_l_0 \wedge at'_l_1$$

$$x' = x - 1 \wedge x' = 0 \rightarrow x = 1$$

it simplifies to

$$pre(\tau_{\ell_0}, \varphi): at_l_0 \wedge x > 0 \rightarrow x = 1$$

Example (cont'd)

$$pre(\tau_{\ell_0}, \varphi): at_{-\ell_0} \wedge x > 0 \rightarrow x = 1$$

Strengthened assertion

$$\varphi \wedge pre(\tau_{\ell_0}, \varphi): (at_{-\ell_1} \rightarrow x = 0) \wedge (at_{-\ell_0} \rightarrow x = 1)$$

what we "guessed" before

Show that $\varphi \wedge pre(\tau_{\ell_0}, \varphi)$ is inductive
("strengthening approach")

Simplification of Precondition

Many transition relations have the form

$$\rho_\tau: C_\tau \wedge \bar{V}' = \bar{E}$$

where C_τ is the enabled condition of τ .

And so

$$pre(\tau, \varphi): \forall \bar{V}'. C_\tau \wedge \bar{V}' = \bar{E} \rightarrow \varphi'$$

can be simplified to

$$\forall \bar{V}'. C_\tau \rightarrow \varphi[\bar{E}/\bar{V}']$$

replacing all primed variables by its
corresponding expression,
thus the quantifier can be eliminated to obtain

$$pre(\tau, \varphi): C_\tau \rightarrow \varphi[\bar{E}/\bar{V}']$$

Mutual Exclusion for Peterson's Algorithm

```
local y1, y2: boolean where y1 = F, y2 = F
      s : integer where s = 1
```

```

P1 ::
  l0 : loop forever do
    [ l1 : noncritical
      l2 : (y1, s) := (T, 1)
      l3 : await (¬y2) ∨ (s = 2)
      l4 : critical
      l5 : y1 := F
    ]

```

||

```

P2 ::
  m0 : loop forever do
    [ m1 : noncritical
      m2 : (y2, s) := (T, 2)
      m3 : await (¬y1) ∨ (s = 1)
      m4 : critical
      m5 : y2 := F
    ]

```

Goal:

Mutual Exclusion for Peterson's algorithm:

$$\square \underbrace{\neg(at_{l_4} \wedge at_{m_4})}_{\psi}$$

Bottom-up invariants:

$$\varphi_0: s = 1 \vee s = 2$$

$$\varphi_1: y_1 \leftrightarrow at_{l_{3..5}}$$

$$\varphi_2: y_2 \leftrightarrow at_{m_{3..5}}$$

Example (cont'd)

```
local y1, y2: boolean where y1 = F, y2 = F
      s : integer where s = 1
```

```

P1 ::
  l0 : loop forever do
    [ l1 : noncritical
      l2 : (y1, s) := (T, 1)
      l3 : await (¬y2) ∨ (s = 2)
      l4 : critical
      l5 : y1 := F
    ]

```

||

```

P2 ::
  m0 : loop forever do
    [ m1 : noncritical
      m2 : (y2, s) := (T, 2)
      m3 : await (¬y1) ∨ (s = 1)
      m4 : critical
      m5 : y2 := F
    ]

```

$$\square \underbrace{\neg(at_{l_4} \wedge at_{m_4})}_{\psi}$$

Problem:

The verification conditions

$$\{\varphi_0 \wedge \varphi_1 \wedge \varphi_2 \wedge \psi\} l_3 \{\psi\}$$

$$\{\varphi_0 \wedge \varphi_1 \wedge \varphi_2 \wedge \psi\} m_3 \{\psi\}$$

are not state-valid.

Example (cont'd)

$$pre(\tau_{l_3}, \psi): \forall \pi': \underbrace{move(l_3, l_4) \wedge (\neg y_2 \vee s \neq 1)}_{\rho_{l_3}} \rightarrow \underbrace{\neg(at_{l_4} \wedge at_{m_4})}_{\psi'}$$

$pre(\tau_{l_3}, \psi)$ simplifies to:

$$at_{l_3} \wedge (\neg y_2 \vee s \neq 1) \rightarrow \neg at_{m_4}$$

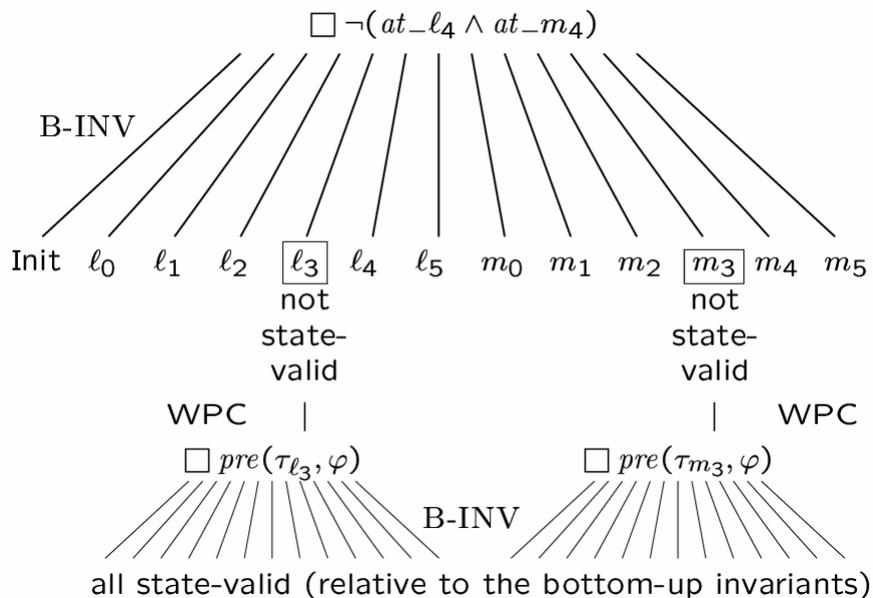
$$\boxed{\varphi_3: at_{l_3} \wedge at_{m_4} \rightarrow y_2 \wedge s = 1}$$

$pre(\tau_{m_3}, \psi): \forall \pi' \dots\dots$

simplifies to:

$$\boxed{\varphi_4: at_{l_4} \wedge at_{m_3} \rightarrow y_1 \wedge s = 2}$$

Example (cont'd)



Completeness of Rule INV

For assertions q, φ	
I1.	$P \models \varphi \rightarrow q$
I2.	$P \models \theta \rightarrow \varphi$
I3.	$P \models \{\varphi\} \mathcal{T} \{\varphi\}$
<hr/>	
	$P \models \Box q$

 INV

For every assertion q such that

$\Box q$ is P -valid

there exists an assertion φ such that I1 – I3
are provable from state validities

Note: We actually show *completeness relative to first-order reasoning*
taking all state-valid assertions as axioms.

Proof Outline

Given FTS P with system variables

$$\bar{y} = (y_1, \dots, y_m)$$

- Assume $\Box q$ is P -valid, i.e.,
(†) q holds over every P -accessible state
- Construct (to be shown) accessibility assertion
 $acc_P(\bar{y})$
such that for any state s ,
(*) s is P -accessible state iff $s \models acc_P$
- Take $\varphi = acc_P$

We have to show :

1. acc_P satisfies I1 – I3
2. acc_P can be constructed

Proof

1. acc_P satisfies I1 – I3

- Premise I1: $\underbrace{acc_P}_{\varphi} \rightarrow q$

$$s \models acc_P \stackrel{(*)}{\Rightarrow} s \text{ is } P\text{-accessible state}$$

$$\stackrel{(\dagger)}{\Rightarrow} s \models q$$

Thus

$$\underbrace{acc_P}_{\varphi} \rightarrow q$$

is state-valid

Proof (cont'd)

- Premise I2: $\Theta \rightarrow \underbrace{acc_P}_{\varphi}$

$$s \models \Theta \Rightarrow s \text{ is } P\text{-accessible}$$

$$\stackrel{(*)}{\Rightarrow} s \models \underbrace{acc_P}_{\varphi}$$

Thus

$$\Theta \rightarrow \underbrace{acc_P}_{\varphi}$$

is state-valid

Proof (cont'd)

- Premise I3: for every $\tau \in \mathcal{T}$,

$$\rho_\tau \wedge acc_P \rightarrow acc'_P$$

where $acc'_P = acc_P(\bar{y}')$.

Take s' to be a \bar{y} -variant of s (s agrees with s' on all variables other than \bar{y}) and for each y_i take

$$s'[y_i] = s[y'_i]$$

Then

$$\left. \begin{array}{l} s \models \rho_\tau \Rightarrow s' \text{ is a } \tau\text{-successor of } s \\ s \models acc_P \stackrel{(*)}{\Rightarrow} s \text{ is } P\text{-accessible} \end{array} \right\} \Rightarrow$$

$$\Rightarrow s' \text{ is } P\text{-accessible}$$

$$\stackrel{(*)}{\Rightarrow} s' \models acc_P$$

$$\Rightarrow s \models acc'_P$$

Proof (cont'd)

2. Construction of acc_P

Assume assertion language includes dynamic array \underline{a} over D

Array \underline{a} is viewed as function,

$$a: [1..n] \mapsto D$$

where n is the size of the array

Assumption is not essential.

E.g., use encoding

$$(n_1, \dots, n_k) \rightarrow n = p_1^{n_1} \dots p_k^{n_k}$$

where p_i is the i th prime number

Proof (cont'd)

Case: single-variable y

Define

$acc_P(y): (\exists n > 0) (\exists a \in [1..n] \mapsto D) . init \wedge last \wedge evolve$

where

$init: \Theta(a[1])$

$last: a[n] = y$

$evolve: \forall i. 1 \leq i < n. \bigvee_{\tau \in \mathcal{T}} \rho_{\tau}(a[i], a[i+1])$

Proof (cont'd)

array a represents a prefix

s_1, \dots, s_n

of a computation where $a[i]$ stands for
the value of y at state s_i

Claim:

For any value $d \in D$,

$acc_P(d) = \top$

iff

d is a possible value of y in a P -accessible state

Proof (cont'd)

Multivariable $\bar{y} = (y_1, \dots, y_m)$ case

Use 2-dimensional array a

$$\begin{array}{cccc} & \underline{y_1} & & \underline{y_m} \\ a[1, 1] & . & . & . & a[1, m] \\ a[2, 1] & . & . & . & a[2, m] \\ & \cdot & & & \cdot \\ & \cdot & & & \cdot \\ & \cdot & & & \cdot \end{array}$$

Example

$$\begin{array}{l} V: \{y\} \quad \text{ranges over } \mathbb{Z} \text{ (the integers)} \\ \Theta: y = 0 \\ \rho_\tau: y' = y + 2 \end{array}$$

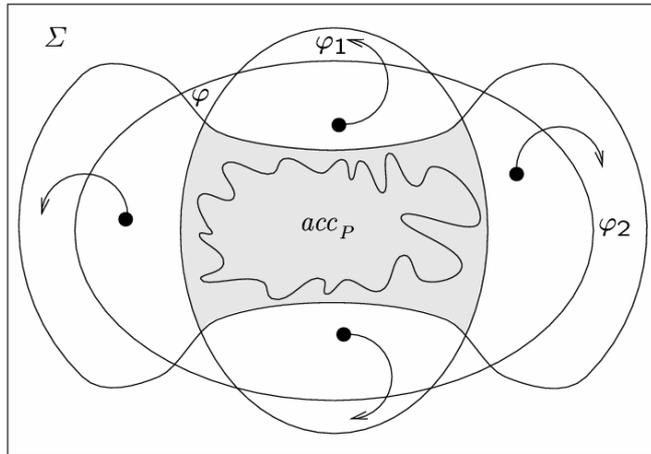
$$acc_P: \quad (\exists n > 0)(\exists a \in [1..n] \mapsto \mathbb{Z}). \\ \left(a[1] = 0 \wedge a[n] = y \wedge \right. \\ \left. \forall i. 1 \leq i < n. a[i+1] = a[i] + 2 \right)$$

simplifies to $(\exists n > 0)(\exists a \in [1..n] \mapsto \mathbb{Z}).$

$$\left(a[n] = y \wedge \right. \\ \left. \forall i. 1 \leq i \leq n. a[i] = 2 \cdot (i - 1) \right)$$

simplifies to $y \geq 0 \wedge \text{even}(y)$

Discussion



Although the assertion acc_P is inductive and strengthens any P -invariant, it is not very useful in practice.