

# Verification

Lecture 16

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## Plan for today

- ▶ LTL bounded model checking
- ▶ Expressiveness of LTL vs. CTL

## REVIEW: Bounded model checking

Search for counterexamples of bounded length

There exists a counterexample of length  $k$  to the invariant  $AGp$  iff the following formula is satisfiable:

$$f_I(\vec{v}_0) \wedge f_{\rightarrow}(\vec{v}_0, \vec{v}_1) \wedge f_{\rightarrow}(\vec{v}_1, \vec{v}_2) \wedge \dots \wedge f_{\rightarrow}(\vec{v}_{k-2}, \vec{v}_{k-1}) \wedge (\neg p_0 \vee \neg p_1 \vee \dots \vee \neg p_{k-1})$$

# Bounded LTL model checking

## Automata-based approach:

- ▶ Translate LTL formula  $\neg\varphi$  to Büchi automaton
- ▶ Build product with transition system
- ▶ Encode all paths that start in initial state and are  $k$  steps long
- ▶ Require that path contains loop with accepting state

$$f_I(\vec{v}_0) \wedge \bigwedge_{i=0}^{k-2} f_{\rightarrow}(\vec{v}_i, \vec{v}_{i+1}) \wedge \bigvee_{i=0}^{k-1} \left( (\vec{v}_i = \vec{v}_k) \wedge \bigvee_{j=i}^{k-1} f_F(\vec{v}_j) \right)$$

Formula size:  $O(k \cdot |TS| \cdot 2^{|\varphi|})$

## Fixpoint-based translation

$$\psi_{TS} \wedge \psi_{loop} \wedge [\psi]_0$$

- ▶  $\psi_{TS} = f_l(\vec{v}_0) \wedge \bigwedge_{i=0}^{k-2} f_{\rightarrow}(\vec{v}_i, \vec{v}_{i+1})$
- ▶  $\psi_{loop}$ : loop constraint, ensures the existence of exactly one loop
- ▶  $[\varphi]_0$ : fixpoint formula, ensures that LTL formula holds

Formula size:  $O(k \cdot (|TS| + |\varphi|))$

## Loop constraint

- ▶  $\psi_{loop} = AtLeastOneLoop \wedge AtMostOneLoop$
- ▶  $AtLeastOneLoop = \bigwedge_{i=0}^{k-2} (l_i \Rightarrow (\vec{v}_i = \vec{v}_{k-1})) \wedge \bigvee_{i=0}^{k-2} l_i$
- ▶  $AtMostOneLoop = \bigwedge_{i=0}^{k-2} (SmallerExists_i \Rightarrow \neg l_i)$
- ▶  $SmallerExists_0 = false$
- ▶  $SmallerExists_{i+1} = SmallerExists_i \vee l_i$  for  $0 \leq i < k - 1$ .

## Fixpoint formula

Let  $\varphi$  be in PNF.

- ▶  $[p]_i = p_i$  for  $i < k - 1$   
 $[p]_i = \bigvee_{j=0}^{k-2} (I_j \wedge p_j)$  for  $i = k - 1$
- ▶  $[\neg p]_i = \neg p_i$  for  $i < k - 1$   
 $[\neg p]_i = \bigvee_{j=0}^{k-2} (I_j \wedge \neg p_j)$  for  $i = k - 1$
- ▶  $[\bigcirc \varphi']_i = [\varphi']_{i+1}$  for  $i < k - 2$   
 $[\bigcirc \varphi']_i = \bigvee_{j=0}^{k-2} (I_j \wedge [\varphi']_j)$  for  $i = k - 2$
- ▶  $[\varphi_1 \mathbf{U} \varphi_2]_i = [\varphi_2]_i \vee ([\varphi_1]_i \wedge [\varphi_1 \mathbf{U} \varphi_2]_{i+1})$  for  $i < k - 1$   
 $[\varphi_1 \mathbf{U} \varphi_2]_i = \bigvee_{j=0}^{k-2} (I_j \wedge \langle \varphi_1 \mathbf{U} \varphi_2 \rangle_j)$  for  $i = k - 1$
- ▶  $[\varphi_1 \mathbf{R} \varphi_2]_i = [\varphi_2]_i \wedge ([\varphi_1]_i \vee [\varphi_1 \mathbf{R} \varphi_2]_{i+1})$  for  $i < k - 1$   
 $[\varphi_1 \mathbf{R} \varphi_2]_i = \bigvee_{j=0}^{k-2} (I_j \wedge \langle \varphi_1 \mathbf{R} \varphi_2 \rangle_j)$  for  $i = k - 1$
- ▶  $\langle \varphi_1 \mathbf{U} \varphi_2 \rangle_i = [\varphi_2]_i \vee ([\varphi_1]_i \wedge \langle \varphi_1 \mathbf{U} \varphi_2 \rangle_{i+1})$  for  $i < k - 1$   
 $\langle \varphi_1 \mathbf{U} \varphi_2 \rangle_i = \text{false}$  for  $i = k - 1$
- ▶  $\langle \varphi_1 \mathbf{R} \varphi_2 \rangle_i = [\varphi_2]_i \wedge ([\varphi_1]_i \vee \langle \varphi_1 \mathbf{R} \varphi_2 \rangle_{i+1})$  for  $i < k - 1$   
 $\langle \varphi_1 \mathbf{R} \varphi_2 \rangle_i = \text{true}$  for  $i = k - 1$

# The Completeness Threshold

The bound  $k$  is **increased incrementally** until

- ▶ a counterexample is found, or
- ▶ the problem becomes intractable due to the complexity of the SAT problem
- ▶  $k$  reaches a precomputed threshold that guarantees that there is no counterexample

→ this threshold is called the **completeness threshold  $CL$** .



# The completeness threshold

- ▶ Computing  $CL$  is as hard as model checking
- ▶ Idea: Compute an overapproximation of  $CL$  based on the graph structure

## Basic notions:

- ▶ **Diameter  $D$** : Longest shortest path between any two reachable states
- ▶ **Recurrence diameter  $RD$** : Longest loop-free path between any two reachable states
- ▶ **Initialized diameter  $D'$** : Longest shortest path between some initial state and some reachable state
- ▶ **Initialized recurrence diameter  $RD'$** : Longest loop-free path between some initial state and some reachable state

# Completeness thresholds

- ▶ For  $\square p$  properties,  $CT \leq D'$ .
- ▶ For  $\diamond p$  properties,  $CT \leq RD' + 1$ .
- ▶ For **general LTL** properties,  $CT \leq \min(RD' + 1, D' + D)$   
(where  $D, D', RD, RD'$  refer to the product graph)

# Complexity

- ▶  $k$  chosen as  $\min(RD^l + 1, D^l + D)$  is exponential in number of state variables
- ▶ Size of SAT instance is  $O(k \cdot (|TS| + |\varphi|))$
- ▶ SAT is solved in exponential time

⇒ double exponential in number of state variables

(Compare: BDD-based model checking is single-exponential)

- ▶ In practice, bounded model checking is very successful
- ▶ Finds shallow errors fast
- ▶ In practice,  $RD, D$  are often not exponential

## Expressiveness of LTL vs. CTL

## Equivalence of LTL and CTL formulas

CTL-formula  $\Phi$  and LTL-formula  $\varphi$  (both over  $AP$ ) are equivalent, denoted  $\Phi \equiv \varphi$ , if for any transition system  $TS$  (over  $AP$ ):

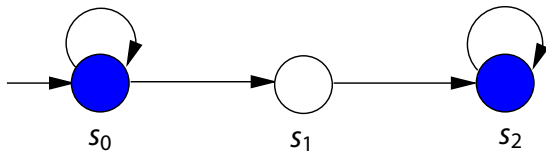
$$TS \models \Phi \quad \text{if and only if} \quad TS \models \varphi$$

## Examples (1)

CTL-formula  $AGAFa$  and LTL-formula  $GFa$  are equivalent.

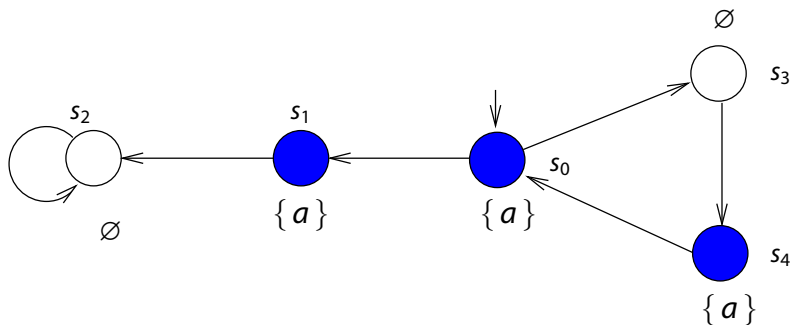
## Examples (2)

$AFAGa$  is **not** equivalent to  $FGa$



## Examples (3)

$F(a \wedge Xa)$  is not equivalent to  $AF(a \wedge AXa)$





# LTL and CTL are incomparable

- ▶ Some LTL-formulas cannot be expressed in CTL, e.g.,
    - ▶  $FGa$
    - ▶  $F(a \wedge Xa)$
  - ▶ Some CTL-formulas cannot be expressed in LTL, e.g.,
    - ▶  $AFAGa$
    - ▶  $AF(a \wedge AXa)$
    - ▶  $AGEFa$
- ⇒ Cannot be expressed = there does not exist an **equivalent** formula

## Example

The CTL-formula  $AG EF a$  cannot be expressed in LTL

## Comparing LTL and CTL

Let  $\Phi$  be a CTL-formula, and  $\varphi$  the LTL-formula obtained by eliminating all path quantifiers in  $\Phi$ . Then: [Clarke & Draghicescu]

$\Phi \equiv \varphi$  or there does not exist any LTL-formula that is equivalent to  $\Phi$

## Comparing LTL and CTL

The LTL-formula  $FG a$  cannot be expressed in CTL