

Verification

Lecture 17

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Plan for today

- ▶ CTL*
- ▶ Bisimulation

REVIEW: LTL and CTL are incomparable

- ▶ Some LTL-formulas cannot be expressed in CTL, e.g.,
 - ▶ FGa
 - ▶ $F(a \wedge Xa)$
 - ▶ Some CTL-formulas cannot be expressed in LTL, e.g.,
 - ▶ $AFAGa$
 - ▶ $AF(a \wedge AXa)$
 - ▶ $AGEFa$
- ⇒ Cannot be expressed = there does not exist an **equivalent** formula

Syntax of CTL*

CTL* state-formulas are formed according to:

$$\Phi ::= \text{true} \mid a \mid \Phi_1 \wedge \Phi_2 \mid \neg\Phi \mid E\varphi$$

where $a \in AP$ and φ is a path-formula

CTL* path-formulas are formed according to the grammar:

$$\varphi ::= \Phi \mid \varphi_1 \wedge \varphi_2 \mid \neg\varphi \mid X\varphi \mid \varphi_1 U \varphi_2$$

where Φ is a state-formula, and φ, φ_1 and φ_2 are path-formulas

$$\text{in CTL}^*: A\varphi = \neg E\neg\varphi.$$

CTL* semantics

$s \models a$	iff	$a \in L(s)$
$s \models \neg \Phi$	iff	not $s \models \Phi$
$s \models \Phi \wedge \Psi$	iff	$(s \models \Phi)$ and $(s \models \Psi)$
$s \models E \varphi$	iff	$\pi \models \varphi$ for some $\pi \in Paths(s)$

$\pi \models \Phi$	iff	$\pi[0] \models \Phi$
$\pi \models \varphi_1 \wedge \varphi_2$	iff	$\pi \models \varphi_1$ and $\pi \models \varphi_2$
$\pi \models \neg \varphi$	iff	not $\pi \models \varphi$
$\pi \models X \Phi$	iff	$\pi[1..] \models \Phi$
$\pi \models \Phi U \Psi$	iff	$\exists j \geq 0. (\pi[j..] \models \Psi \wedge (\forall 0 \leq k < j. \pi[k..] \models \Phi))$

Transition system semantics

- ▶ For CTL^{*}-state-formula Φ , the satisfaction set $Sat(\Phi)$ is defined by:

$$Sat(\Phi) = \{ q \in S \mid q \models \Phi \}$$

- ▶ TS satisfies CTL^{*}-formula Φ iff Φ holds in all its initial states:

$$TS \models \Phi \quad \text{if and only if} \quad \forall q \in I. q_0 \models \Phi$$

this is exactly as for CTL

Embedding of LTL in CTL*

For LTL formula φ and TS without terminal states (both over AP) and for each $q \in S$:

$$\underbrace{q \models \varphi}_{\text{LTL semantics}} \quad \text{if and only if} \quad \underbrace{q \models A\varphi}_{\text{CTL}^* \text{ semantics}}$$

In particular:

$$TS \models_{LTL} \varphi \quad \text{if and only if} \quad TS \models_{CTL^*} A\varphi$$

CTL* is more expressive than LTL and CTL

For the CTL*-formula over $AP = \{a, b\}$:

$$\Phi = (AFG a) \vee (AGEF b)$$

there does not exist any equivalent LTL or CTL formula

CTL⁺ state-formulas are formed according to:

$$\Phi ::= \text{true} \mid a \mid \Phi_1 \wedge \Phi_2 \mid \neg\Phi \mid E\varphi \mid A\varphi$$

where $a \in AP$ and φ is a path-formula

CTL⁺ path-formulas are formed according to the grammar:

$$\varphi ::= \varphi_1 \wedge \varphi_2 \mid \neg\varphi \mid X\Phi \mid \Phi_1 U \Phi_2$$

where Φ, Φ_1, Φ_2 are state-formulas, and φ, φ_1 and φ_2 are path-formulas

CTL⁺ is as expressive as CTL

For example:

$$\underbrace{E(Fa \wedge Fb)}_{\text{CTL}^+ \text{ formula}} \equiv \underbrace{EF(a \wedge EFb) \vee EF(b \wedge EFa)}_{\text{CTL formula}}$$

Some rules for transforming CTL⁺ formulas into equivalent CTL formulas:

$$E(\neg(\Phi_1 U \Phi_2)) \equiv E((\Phi_1 \wedge \neg\Phi_2) U (\neg\Phi_1 \wedge \neg\Phi_2)) \vee EG\neg\Phi_2$$

$$E(X\Phi_1 \wedge X\Phi_2) \equiv EX(\Phi_1 \wedge \Phi_2)$$

$$E(X\Phi \wedge (\Phi_1 U \Phi_2)) \equiv (\Phi_2 \wedge EX\Phi) \vee (\Phi_1 \wedge EX(\Phi \wedge E(\Phi_1 U \Phi_2)))$$

$$E((\Phi_1 U \Phi_2) \wedge (\Psi_1 U \Psi_2)) \equiv E((\Phi_1 \wedge \Psi_1) U (\Phi_2 \wedge E(\Psi_1 U \Psi_2))) \vee \\ E((\Phi_1 \wedge \Psi_1) U (\Psi_2 \wedge E(\Phi_1 U \Phi_2))) \\ \vdots$$

adding boolean combinations of path formulas to CTL does not change its
expressiveness

but CTL⁺ formulas can be much shorter than shortest equivalent CTL formulas

CTL* model checking

- ▶ Adopt the same bottom-up procedure as for (fair) CTL
- ▶ Replace each maximal proper state subformula Ψ by new proposition a_Ψ
 - ▶ $a_\Psi \in L(s)$ if and only if $s \in \text{Sat}(\Psi)$
- ▶ Most interesting case: formulas of the form $E \varphi$
 - ▶ by replacing all maximal state sub-formulas in φ , an LTL-formula results!
- ▶ $q \models E \varphi$ iff $\underbrace{q \not\models A \neg \varphi}_{\text{CTL}^* \text{ semantics}}$ iff $\underbrace{q \not\models \neg \varphi}_{\text{LTL semantics}}$
 - ▶ $\text{Sat}_{\text{CTL}^*}(E \varphi) = S \setminus \text{Sat}_{\text{LTL}}(\neg \varphi)$

CTL* model-checking algorithm

for all $i \leq |\Phi|$ **do**

for all $\Psi \in \text{Sub}(\Phi)$ with $|\Psi| = i$ **do**

switch(Ψ):

true : $\text{Sat}(\Psi) := S$;

a : $\text{Sat}(\Psi) := \{q \in S \mid a \in L(q)\}$;

$a_1 \wedge a_2$: $\text{Sat}(\Psi) := \text{Sat}(a_1) \cap \text{Sat}(a_2)$;

$\neg a$: $\text{Sat}(\Psi) := S \setminus \text{Sat}(a)$;

$E\varphi$: determine $\text{Sat}_{LTL}(\neg\varphi)$ by means of an LTL model checker;

: $\text{Sat}(\Psi) := S \setminus \text{Sat}_{LTL}(\neg\varphi)$

end switch

$AP := AP \cup \{a_\Psi\}$; {introduce fresh atomic proposition}

replace Ψ with a_Ψ

forall $q \in \text{Sat}(\Psi)$ **do** $L(q) := L(q) \cup \{a_\Psi\}$; **od**

end for

end for

return $I \subseteq \text{Sat}(\Phi)$

Time complexity

For transition system TS with N states and M transitions, CTL* formula Φ , the CTL* model-checking problem $TS \models \Phi$ can be determined in time $\mathcal{O}((N+M) \cdot 2^{|\Phi|})$.

the CTL* model-checking problem is PSPACE-complete

Bisimulation

Implementation relations

- ▶ A binary relation on transition systems
 - ▶ when does a transition systems correctly implement another?
- ▶ Important for system synthesis
 - ▶ stepwise refinement of a system specification TS into an “implementation” TS'
- ▶ Important for system analysis
 - ▶ use the implementation relation as a means for abstraction
 - ▶ replace $TS \models \varphi$ by $TS' \models \varphi$ where $|TS'| \ll |TS|$ such that:

$$TS \models \varphi \text{ iff } TS' \models \varphi \quad \text{or} \quad TS' \models \varphi \Rightarrow TS \models \varphi$$

- ⇒ Focus on state-based bisimulation and simulation
- ▶ logical characterization: which logical formulas are preserved by bisimulation?

Bisimulation equivalence

Let $TS_i = (S_i, Act_i, \rightarrow_i, l_i, AP, L_i)$, $i=1, 2$, be transition systems

A bisimulation for (TS_1, TS_2) is a binary relation $\mathcal{R} \subseteq S_1 \times S_2$ such that:

1. $\forall s_1 \in I_1 \exists s_2 \in I_2. (s_1, s_2) \in \mathcal{R}$ and $\forall s_2 \in I_2 \exists s_1 \in I_1. (s_1, s_2) \in \mathcal{R}$
2. for all states $s_1 \in S_1, s_2 \in S_2$ with $(s_1, s_2) \in \mathcal{R}$ it holds:
 - 2.1 $L_1(s_1) = L_2(s_2)$
 - 2.2 if $s'_1 \in Post(s_1)$ then there exists $s'_2 \in Post(s_2)$ with $(s'_1, s'_2) \in \mathcal{R}$
 - 2.3 if $s'_2 \in Post(s_2)$ then there exists $s'_1 \in Post(s_1)$ with $(s'_1, s'_2) \in \mathcal{R}$

TS_1 and TS_2 are bisimilar, denoted $TS_1 \sim TS_2$, if there exists a bisimulation for (TS_1, TS_2)

Bisimulation equivalence

$$q_1 \rightarrow q'_1$$

\mathcal{R}

q_2

can be completed to

$$q_1 \rightarrow q'_1$$

\mathcal{R} \mathcal{R}

$$q_2 \rightarrow q'_2$$

and

q_1

\mathcal{R}

$$q_2 \rightarrow q'_2$$

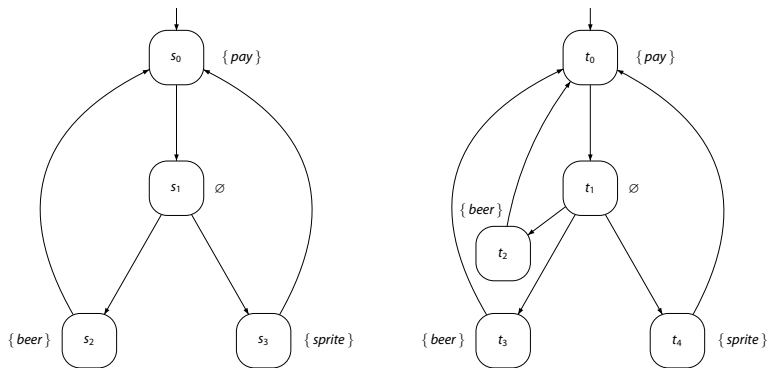
can be completed to

$$q_1 \rightarrow q'_1$$

\mathcal{R} \mathcal{R}

$$q_2 \rightarrow q'_2$$

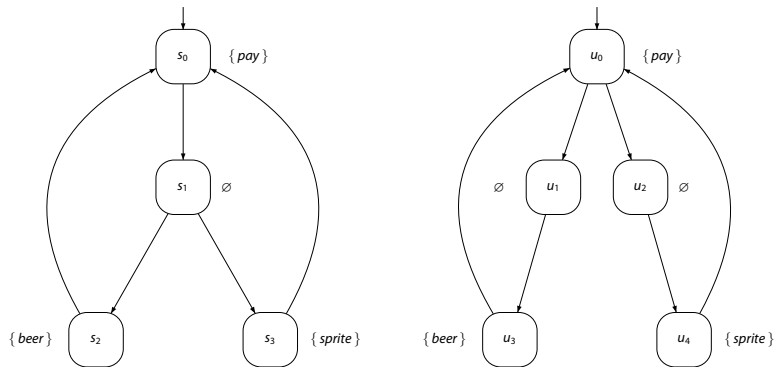
Example (1)



$$\mathcal{R} = \{(s_0, t_0), (s_1, t_1), (s_2, t_2), (s_2, t_3), (s_3, t_4)\}$$

is a bisimulation for (TS_1, TS_2) where $AP = \{pay, beer, sprite\}$

Example (2)



$TS_1 \not\sim TS_3$ for $AP = \{pay, beer, sprite\}$

But: $\{(s_0, u_0), (s_1, u_1), (s_1, u_2), (s_2, u_3), (s_2, u_4), (s_3, u_3), (s_3, u_4)\}$

is a bisimulation for (TS_1, TS_3) for $AP = \{pay, drink\}$

\sim is an equivalence

For any transition systems TS, TS_1, TS_2 and TS_3 over AP :

$TS \sim TS$ (reflexivity)

$TS_1 \sim TS_2$ implies $TS_2 \sim TS_1$ (symmetry)

$TS_1 \sim TS_2$ and $TS_2 \sim TS_3$ implies $TS_1 \sim TS_3$ (transitivity)

Bisimulation on paths

Whenever we have:

$$\begin{array}{ccccccccc} s_0 & \rightarrow & s_1 & \rightarrow & s_2 & \rightarrow & s_3 & \rightarrow & s_4 \dots\dots \\ \mathcal{R} & & & & & & & & \\ t_0 & & & & & & & & \end{array}$$

this can be completed to

$$\begin{array}{ccccccccc} s_0 & \rightarrow & s_1 & \rightarrow & s_2 & \rightarrow & s_3 & \rightarrow & s_4 \dots\dots \\ \mathcal{R} & & \mathcal{R} & & \mathcal{R} & & \mathcal{R} & & \mathcal{R} \\ t_0 & \rightarrow & t_1 & \rightarrow & t_2 & \rightarrow & t_3 & \rightarrow & t_4 \dots\dots \end{array}$$

proof: by induction on index i of state s_i

Bisimulation vs. trace equivalence

$TS_1 \sim TS_2$ implies $Traces(TS_1) = Traces(TS_2)$

bisimilar transition systems thus satisfy the same LT properties!

Bisimulation on states

$\mathcal{R} \subseteq S \times S$ is a bisimulation on TS if for any $(q_1, q_2) \in \mathcal{R}$:

- ▶ $L(q_1) = L(q_2)$
- ▶ if $q'_1 \in Post(q_1)$ then there exists an $q'_2 \in Post(q_2)$ with $(q'_1, q'_2) \in \mathcal{R}$
- ▶ if $q'_2 \in Post(q_2)$ then there exists an $q'_1 \in Post(q_1)$ with $(q'_1, q'_2) \in \mathcal{R}$

q_1 and q_2 are bisimilar, $q_1 \sim_{TS} q_2$, if $(q_1, q_2) \in \mathcal{R}$ for some bisimulation \mathcal{R} for TS

$$q_1 \sim_{TS} q_2 \quad \text{if and only if} \quad TS_{q_1} \sim TS_{q_2}$$

Coarsest bisimulation

\sim_{TS} is an equivalence and the coarsest bisimulation for TS

Quotient transition system

For $TS = (S, Act, \rightarrow, I, AP, L)$ and bisimulation $\sim_{TS} \subseteq S \times S$ on TS let

$TS/\sim_{TS} = (S', \{\tau\}, \rightarrow', I', AP, L')$, the quotient of TS under \sim_{TS}

where

- ▶ $S' = S/\sim_{TS} = \{ [s]_{\sim} \mid s \in S \}$ with $[s]_{\sim} = \{ s' \in S \mid s \sim_{TS} s' \}$
- ▶ \rightarrow' is defined by:
$$\frac{s \xrightarrow{\alpha} s'}{[s]_{\sim} \xrightarrow{\tau'} [s']_{\sim}}$$
- ▶ $I' = \{ [s]_{\sim} \mid s \in I \}$
- ▶ $L'([s]_{\sim}) = L(s)$

The Bakery algorithm

$$P_1 :: \left[\begin{array}{l} \text{loop forever do} \\ \left[\begin{array}{l} \text{noncritical} \\ n_1 : y_1 := y_2 + 1 \\ w_1 : \text{await } (y_2 = 0 \vee y_1 < y_2) \\ c_1 : \text{critical} \\ y_1 := 0 \end{array} \right] \end{array} \right]$$
$$\parallel P_2 :: \left[\begin{array}{l} \text{loop forever do} \\ \left[\begin{array}{l} \text{noncritical} \\ n_2 : y_2 := y_1 + 1 \\ w_2 : \text{await } (y_1 = 0 \vee y_2 < y_1) \\ c_2 : \text{critical} \\ y_2 := 0 \end{array} \right] \end{array} \right]$$

Example path fragment

process P_1	process P_2	y_1	y_2	effect
n_1	n_2	0	0	P_1 requests access to critical section
w_1	n_2	1	0	P_2 requests access to critical section
w_1	w_2	1	2	P_1 enters the critical section
c_1	w_2	1	2	P_1 leaves the critical section
n_1	w_2	0	2	P_1 requests access to critical section
w_1	w_2	3	2	P_2 enters the critical section
w_1	c_2	3	2	P_2 leaves the critical section
w_1	n_2	3	0	P_2 requests access to critical section
w_1	w_2	3	4	P_1 enters the critical section
...

Data abstraction

Function f maps a reachable state of TS_{Bak} onto an abstract one in TS_{Bak}^{abs}
Let $s = \langle \ell_1, \ell_2, y_1 = b_1, y_2 = b_2 \rangle$ be a state of TS_{Bak} with $\ell_i \in \{n_i, w_i, c_i\}$ and $b_i \in \mathbb{N}$

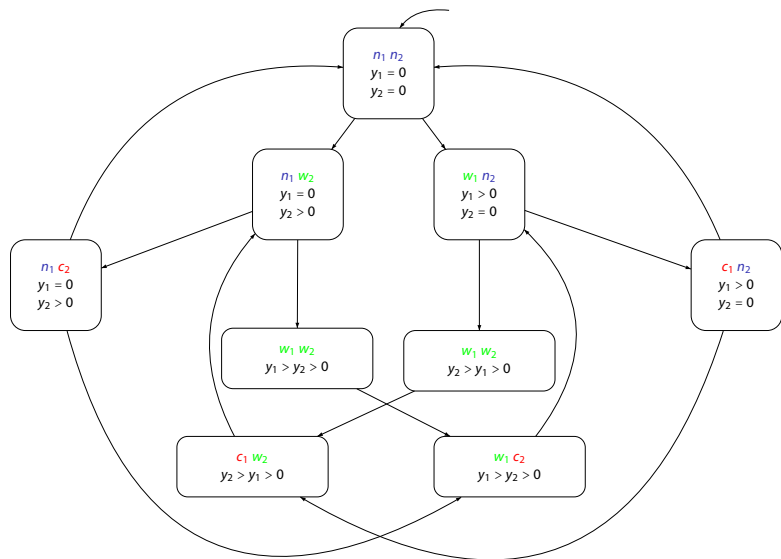
Then:

$$f(s) = \begin{cases} \langle \ell_1, \ell_2, y_1 = 0, y_2 = 0 \rangle & \text{if } b_1 = b_2 = 0 \\ \langle \ell_1, \ell_2, y_1 = 0, y_2 > 0 \rangle & \text{if } b_1 = 0 \text{ and } b_2 > 0 \\ \langle \ell_1, \ell_2, y_1 > 0, y_2 = 0 \rangle & \text{if } b_1 > 0 \text{ and } b_2 = 0 \\ \langle \ell_1, \ell_2, y_1 > y_2 > 0 \rangle & \text{if } b_1 > b_2 > 0 \\ \langle \ell_1, \ell_2, y_2 > y_1 > 0 \rangle & \text{if } b_2 > b_1 > 0 \end{cases}$$

$\mathcal{R} = \{ (s, f(s)) \mid s \in S \}$ is a bisimulation for $(TS_{Bak}, TS_{Bak}^{abs})$

for any subset of $AP = \{ noncrit_i, wait_i, crit_i \mid i = 1, 2 \}$

Bisimulation quotient



$$TS_{Bak}^{abs} = TS_{Bak} / \sim \quad \text{for } AP = \{crit_1, crit_2\}$$

Remarks

- ▶ In this example, data abstraction yields a bisimulation relation
 - ▶ (typically, only a simulation relation is obtained, more later)
- ▶ $TS_{Bak}^{abs} \models \varphi$ with, e.g.,:
 - ▶ $\Box(\neg crit_1 \vee \neg crit_2)$ and $(\Box \Diamond wait_1 \Rightarrow \Box \Diamond crit_1) \wedge (\Box \Diamond wait_2 \Rightarrow \Box \Diamond crit_2)$
- ▶ Since $TS_{Bak}^{abs} \sim TS_{Bak}$, it follows $TS_{Bak} \models \varphi$
- ▶ Note: $Traces(TS_{Bak}^{abs}) = Traces(TS_{Bak})$

CTL* equivalence

States q_1 and q_2 in TS (over AP) are **CTL*-equivalent**:

$$q_1 \equiv_{\text{CTL}^*} q_2 \quad \text{if and only if} \quad (q_1 \models \Phi \text{ iff } q_2 \models \Phi)$$

for all CTL* state formulas over AP

$$TS_1 \equiv_{\text{CTL}^*} TS_2 \quad \text{if and only if} \quad (TS_1 \models \Phi \text{ iff } TS_2 \models \Phi)$$

for any sublogic of CTL*, logical equivalence is defined analogously

Bisimulation vs. CTL* and CTL equivalence

Let TS be a finite state graph and s, s' states in TS

The following statements are equivalent:

- (1) $s \sim_{TS} s'$
- (2) s and s' are CTL-equivalent, i.e., $s \equiv_{CTL} s'$
- (3) s and s' are CTL*-equivalent, i.e., $s \equiv_{CTL^*} s'$

this is proven in three steps: $\equiv_{CTL} \subseteq \sim \subseteq \equiv_{CTL^*} \subseteq \equiv_{CTL}$

important: equivalence is also obtained for any sub-logic containing \neg, \wedge and X

The importance of this result

- ▶ CTL and CTL* equivalence coincide
 - ▶ despite the fact that CTL* is more expressive than CTL
- ▶ Bisimilar transition systems preserve the same CTL* formulas
 - ▶ and thus the same LTL formulas (and LT properties)
- ▶ Non-bisimilarity can be shown by a single CTL (or CTL*) formula
 - ▶ $TS_1 \models \Phi$ and $TS_2 \not\models \Phi$ implies $TS_1 \not\sim TS_2$
- ▶ You even do not need to use an until-operator!
- ▶ To check $TS \models \Phi$, it suffices to check $TS / \sim \models \Phi$