

Verification

Lecture 26

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Plan for today

- ▶ Deductive verification: basic mechanics
 - ▶ Partial correctness
 - ▶ Total correctness

Deductive verification

Verification of infinite-state programs
based on automatic decision procedures

Textbooks:

Bradley/Manna, *The Calculus of Computation*

- ▶ sequential programs
- ▶ first-order logic
- ▶ inductive assertions, ranking functions
- ▶ decision procedures

Manna/Pnueli: *Temporal Verification of Reactive Systems*

- ▶ reactive programs
- ▶ temporal logic
- ▶ verification rules and diagrams

Example: Linear search

```
bool LinearSearch(int[] a, int l, int u, int e) {  
    for @ T  
        (int i := l; i ≤ u; i := i + 1) {  
            if (a[i] = e) return true;  
        }  
    return false;  
}
```

Function specification

```
@pre  $0 \leq l \wedge u < |a|$ 
@post  $rv \leftrightarrow \exists i. l \leq i \leq u \wedge a[i] = e$ 
bool LinearSearch(int[] a, int l, int u, int e) {
    for @ T
        (int i := l; i ≤ u; i := i + 1) {
            if (a[i] = e) return true;
        }
    return false;
}
```

- ▶ **Precondition:** Function guaranteed to behave correctly if $0 \leq l$ and $u < |a|$
- ▶ **Postcondition:** Function returns true iff a contains value e in the range $[l, u]$.

Example: Binary search

```
@pre  $0 \leq l \wedge u < |a| \wedge sorted(a, l, u)$ 
@post  $rv \leftrightarrow \exists i. l \leq i \leq u \wedge a[i] = e$ 
bool BinarySearch(int[] a, int l, int u, int e) {
    if  $l > u$  return false;
    else {
        int m := ( $l + u$ ) div 2;
        if ( $a[m] = e$ ) return true;
        else if ( $a[m] < e$ ) return BinarySearch(a, m + 1, u, e);
        else return BinarySearch(a, l, m - 1, e);
    }
}
```

sorted: weakly increasing order, i.e.,

$$sorted(a, l, u) \Leftrightarrow \forall i, j. l \leq i \leq j \leq u \rightarrow a[i] \leq a[j]$$

Example: Bubble sort

```
@pre T
@post sorted(rv, 0, |rv| - 1)
int[] BubbleSort(int[] a0) {
    int[] a := a0;
    for @ T
        (int i := |a| - 1; i > 0; i := i - 1) {
            for @ T
                (int j := 0; j < i; j := j + 1) {
                    if (a[j] > a[j + 1]) {
                        int t := a[j];
                        a[j] := a[j + 1];
                        a[j + 1] := t;
                    }
                }
            }
        }
    return a;
```

Loop invariants

```
while          for
@ F           @ F
(<condition>) {
  <body>
}
              (<init>; <cond>; <incr>) {
  <body>
}
```

- ▶ $\langle \text{body} \rangle$ is applied as long as $\langle \text{condition} \rangle$ holds
- ▶ Assertion F must hold in every iteration
- ▶ F is evaluated before $\langle \text{condition} \rangle$
⇒ must hold even on final iteration
when $\langle \text{condition} \rangle$ is false

Example: linear search

```
@pre  $0 \leq l \wedge u < |a|$ 
@post  $rv \leftrightarrow \exists i. l \leq i \leq u \wedge a[i] = e$ 
bool LinearSearch(int[] a, int l, int u, int e) {
    for @ $L: l \leq i \wedge (\forall j. l \leq j < i \rightarrow a[j] \neq e)$ 
        (int i := l; i ≤ u; i := i + 1) {
            if (a[i] = e) return true;
        }
    return false;
}
```

Assertions

@ F

- ▶ Assertions can be added anywhere
- ▶ Assertions are “formal comments”
- ▶ Special class: **runtime assertions**
refer to runtime errors such as
 - ▶ division by 0
 - ▶ array access out of bounds

Example: Binary search

```
@pre  $0 \leq l \wedge u < |a| \wedge sorted(a, l, u)$ 
@post  $rv \leftrightarrow \exists i. l \leq i \leq u \wedge a[i] = e$ 
bool BinarySearch(int[] a, int l, int u, int e) {
    if  $l > u$  return false;
    else {
        @  $2 \neq 0$ 
        int m :=  $(l + u)$  div 2;
        @  $0 \leq m < |a|$ 
        if  $(a[m] = e)$  return true;
        @  $0 \leq m < |a|$ 
        else if  $(a[m] < e)$  return BinarySearch(a, m + 1, u, e);
        else return BinarySearch(a, l, m - 1, e);
    }
}
```

Partial Correctness

A function is **partially correct** if

- ▶ when the function's **precondition** is satisfied on entry,
- ▶ its **postcondition** is satisfied when the function returns (**if it ever does**).

Inductive assertion method

- ▶ Each function and its annotation are reduced to a finite set of **verification conditions** (VCs)
- ▶ VCs are formulas of first-order logic
- ▶ If all VCs are valid, then the function is partially correct.

Basic paths

We break the program into **basic paths**:

@ precondition or loop invariant

sequence of **instructions**
(no loop invariants)

@ loop invariant, assertion, or postcondition

- ▶ loops and recursive calls produce an **unbounded** number of paths
- ▶ loop invariants “**cut loops**” into a finite set of basic paths
- ▶ function specifications “**cut function calls**” into a finite set of basic paths

Basic paths: Linear search

```
@pre  $0 \leq l \wedge u < |a|$ 
@post  $rv \leftrightarrow \exists i. l \leq i \leq u \wedge a[i] = e$ 
bool LinearSearch(int[] a, int l, int u, int e) {
    for @ L :  $l \leq i \wedge (\forall j. l \leq j < i \rightarrow a[j] \neq e)$ 
        (int i := l; i ≤ u; i := i + 1) {
            if (a[i] = e) return true;
        }
    return false;
}
```

(1) @pre $0 \leq l \wedge u < |a|$

$i := l$

@ L : $l \leq i \wedge (\forall j. l \leq j < i \rightarrow a[j] \neq e)$

(2) @ L : $l \leq i \wedge (\forall j. l \leq j < i \rightarrow a[j] \neq e)$

assume $i \leq u$;

assume $a[i] = e$;

$rv := \text{true}$

@post $rv \leftrightarrow \exists i. l \leq i \leq u \wedge a[i] = e$

(3) @ L : $l \leq i \wedge (\forall j. l \leq j < i \rightarrow a[j] \neq e)$

assume $i \leq u$;

assume $a[i] \neq e$;

$i := i + 1$

@ L : $l \leq i \wedge (\forall j. l \leq j < i \rightarrow a[j] \neq e)$

(4) @ L : $l \leq i \wedge (\forall j. l \leq j < i \rightarrow a[j] \neq e)$

assume $i > u$;

$rv := \text{false}$

@post $rv \leftrightarrow \exists i. l \leq i \leq u \wedge a[i] = e$

Function call assertions: Binary search

```
@pre  $0 \leq l \wedge u < |a| \wedge \text{sorted}(a, l, u)$ 
@post  $rv \leftrightarrow \exists i. l \leq i \leq u \wedge a[i] = e$ 
bool BinarySearch(int[] a, int l, int u, int e) {
    if  $l > u$  return false;
    else {
        int  $m := (l + u) \text{ div } 2$ ;
        if  $(a[m] = e)$  return true;
        else if  $(a[m] < e)$  {
            @R1 :  $0 \leq m + 1 \wedge u < |a| \wedge \text{sorted}(a, m + 1, u)$ 
            return BinarySearch(a, m + 1, u, e);
        } else {
            @R2 :  $0 \leq l \wedge m - 1 < |a| \wedge \text{sorted}(a, l, m - 1)$ 
            return BinarySearch(a, l, m - 1, e);
        }
    }
}
```

Function call assertion R_1 results from precondition

$F[a, l, u, e] : 0 \leq l \wedge u < |a| \wedge \text{sorted}(a, l, u)$ as $R_1 = F[a, m + 1, u, e]$

Function summary: Binary search

(3) @pre $0 \leq l \wedge u < |a| \wedge \text{sorted}(a, l, u)$
assume $l \leq u$;
 $m := (l + u) \text{ div } 2$;
assume $a[m] \neq e$;
assume $a[m] < e$;
@ $R_1 : 0 \leq m + 1 \wedge u < |a| \wedge \text{sorted}(a, m + 1, u)$

(4) @pre $0 \leq l \wedge u < |a| \wedge \text{sorted}(a, l, u)$
assume $l \leq u$;
 $m := (l + u) \text{ div } 2$;
assume $a[m] \neq e$;
assume $a[m] < e$;
assume $v_1 \leftrightarrow \exists i. m + 1 \leq i \leq u \wedge a[i] = e$;
 $rv := v_1$;
@post $rv \leftrightarrow \exists i. l \leq i \leq u \wedge a[i] = e$

Function summary results from function postcondition @post
 $G[a, l, u, e, rv] : rv \leftrightarrow \exists i. l \leq i \leq u \wedge a[i] = e$

- ▶ Introduce a fresh variable (v_1)
- ▶ Assume that the function postcondition holds
assume $G[a, m + 1, u, e, v_1]$.

Program states

- ▶ Program counter pc holds current location of control
- ▶ State s is an assignment of values (of proper type) to all variables

Example:

$$s : \left\{ \begin{array}{l} pc \mapsto L, \\ a \mapsto [0; 1; 2], i \mapsto 3 \end{array} \right\}$$

is a state of LinearSearch

- ▶ Reachable state s is a state that can be reached during some computation

Example:

$$s : \left\{ \begin{array}{l} pc \mapsto L, \\ a \mapsto [0; 1; 2], i \mapsto 2 \end{array} \right\}$$

is a reachable state of LinearSearch

Weakest precondition

- ▶ A predicate transformer is a function

$$p : \text{FOL} \times \text{stmts} \rightarrow \text{FOL}$$

that maps a formula of first-order logic and a statement to another formula of first-order logic.

- ▶ The weakest precondition $wp(F, S)$ is a predicate transformer such that for every state s with

$$s \models wp(F, S),$$

if statement S is executed on s to produce s' , then

$$s' \models F.$$

Verification condition

- $wp(F, \text{assume } c) \Leftrightarrow c \rightarrow F$
- $wp(F[v], v := e) \Leftrightarrow F[e]$
- $wp(F, S_1; S_2; \dots; S_{n-1}; S_n) \Leftrightarrow wp(wp(F, S_n), S_1; S_2; \dots; S_{n-1})$

The verification condition of basic path

$\text{@ } F$

$S_1;$

...

$S_n;$

$\text{@ } G$

is

$$F \rightarrow wp(G, S_1; \dots; S_n).$$

Traditionally, this verification condition is denoted by the
Hoare triple $\{F\} S_1; \dots; S_n \{G\}$.

Example: Linear search

(2) $\text{@}L : F : l \leq i \wedge (\forall j. l \leq j < i \rightarrow a[j] \neq e)$

$S_1 : \text{assume } i \leq u$

$S_2 : \text{assume } a[i] = e$

$S_3 : rv := \text{true}$

$\text{@post } G : rv \leftrightarrow \exists i. l \leq i \leq u \wedge a[i] = e$

The VC of basic path (2) is

$$F \rightarrow wp(G, S_1; S_2; S_3).$$

We compute

$$\begin{aligned} & wp(G, S_1; S_2; S_3) \\ \Leftrightarrow & wp(wp(rv \leftrightarrow \exists i. l \leq i \leq u \wedge a[i] = e, rv := \text{true}), S_1; S_2) \\ \Leftrightarrow & wp(\exists i. l \leq i \leq u \wedge a[i] = e, S_1; S_2) \\ \Leftrightarrow & wp(wp(\exists i. l \leq i \leq u \wedge a[i] = e, \text{assume } a[i] = e), S_1) \\ \Leftrightarrow & wp(a[i] = e \rightarrow \exists i. l \leq i \leq u \wedge a[i] = e, \text{assume } i \leq u) \\ \Leftrightarrow & i \leq u \rightarrow (a[i] = e \rightarrow \exists i. l \leq i \leq u \wedge a[i] = e) \end{aligned}$$

Example: Linear search

(2) $\text{@}L : F : I \leq i \wedge (\forall j. I \leq j < i \rightarrow a[j] \neq e)$

$S_1 : \text{assume } i \leq u$

$S_2 : \text{assume } a[i] = e$

$S_3 : rv := \text{true}$

$\text{@post } G : rv \leftrightarrow \exists i. I \leq i \leq u \wedge a[i] = e$

The VC of basic path (2) is

$$F \rightarrow wp(G, S_1; S_2; S_3).$$

We compute

$$wp(G, S_1; S_2; S_3) \Leftrightarrow i \leq u \rightarrow (a[i] = e \rightarrow \exists i. I \leq i \leq u \wedge a[i] = e)$$

Hence, the VC is

$$I \leq i \wedge (\forall j. I \leq j < i \rightarrow a[j] \neq e)$$

$$\rightarrow (i \leq u \rightarrow (a[i] = e \rightarrow \exists i. I \leq i \leq u \wedge a[i] = e)),$$

which is valid.

Computations

- ▶ Consider program P with function f , function precondition F_{pre} and initial location L_0 .
- ▶ A P -computation is a sequence of states

$$s_0, s_1, s_2, \dots$$

such that

- ▶ $s_0[pc] = L_0$ and $s_0 \models F_{pre}$, and
- ▶ for each i , s_{i+1} is the result of executing the instruction at $s_i[pc]$ on state s_i .

Notation: $s_i[pc] = \text{value of } pc \text{ given by state } s_i$.

P -invariant and P -inductive

A formula F annotating location L of program P is P -invariant if for all P -computations s_0, s_1, s_2, \dots and for each index i ,

$$s_i[pc] = L \Rightarrow s_i \models F$$

Annotations of P are P -invariant iff each annotation of P is P -invariant at its location.

Note: this definition is not implementable. Checking if F is P -invariant requires an infinite number of P -computations in general.

P -inductive

Instead, we check if the annotations are P -inductive.

Annotations of P are P -inductive iff all VCs generated from the basic paths of program P are valid.

P -inductive $\Rightarrow P$ -invariant

Theorem (Verification Conditions)

If for every basic path

$\text{@ } L_1 : F$

S_1

\vdots

S_n

$\text{@ } L_j : G$

of program P , the verification condition

$$\{F\} S_1; \dots; S_n \{G\}$$

is valid, then the annotations are P -inductive, and therefore P -invariant.

If there is a P -invariant annotation, then P is partially correct.

Example: Bubble sort

```
@pre T
@post sorted(rv, 0, |rv| - 1)
int[] BubbleSort(int[] a0) {
    int[] a := a0;
    for @ L1
        (int i := |a| - 1; i > 0; i := i - 1) {
            for @ L2
                (int j := 0; j < i; j := j + 1) {
                    if (a[j] > a[j + 1]) {
                        int t := a[j];
                        a[j] := a[j + 1];
                        a[j + 1] := t;
                    }
                }
            }
        }
    return a;
```

Example: Bubble sort

```
@pre  $\top$ 
@post sorted(rv, 0, |rv| - 1)
int[] BubbleSort(int[] a0) {
    int[] a := a0;                                L1 :  $-1 \leq i < |a|$ 
    for @ L1                                      $\wedge$  partitioned(a, 0, i, i + 1, |a| - 1)
        (int i := |a| - 1; i > 0; i := i - 1) {    $\wedge$  sorted(a, i, |a| - 1)
            for @ L2
                (int j := 0; j < i; j := j + 1) { L2 :  $1 \leq i < |a| \wedge 0 \leq j \leq i$ 
                    if (a[j] > a[j + 1]) {
                        int t := a[j];
                        a[j] := a[j + 1];
                        a[j + 1] := t;
                    }
                }                                         partitioned(a, l1, u1, l2, u2)
            }                                          $\Leftrightarrow \forall i, j. l_1 \leq i \leq u_1 < l_2 \leq j \leq u_2 \rightarrow a[i] \leq a[j]$ 
        }
    return a;
```